

News Media and Delegated Information Choice

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October 2, 2017

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The man who buys a newspaper does not know beforehand what will be in the news.

Jacob Marschak, 1960

Public Information and Coordination

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But what do we mean when we say that information is *public*?

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We ask: How do editorial decisions affect the degree to which information about specific events is common knowledge?

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- ▶ Heterogenous agents rely on specialized information providers to monitor the world on their behalf
- ▶ The degree to which information about an event is common among agents is endogenous
- ▶ Analyze how the editorial function of news media affect agents beliefs and actions

Measuring News Coverage

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Main Advantages:

- ▶ Objective and the results can be replicated
- ▶ Naturally measures the relative importance of topics

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The number of topics is set to 10 in our benchmark specification

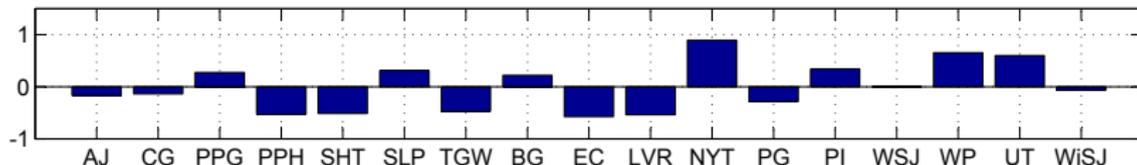
Newspaper Sources

| Newspaper Full Name | Short Name | Newspaper Full Name | Short Name |
|------------------------------|-------------------|------------------------------|-------------------|
| Atlanta Journal | AJ | The Las Vegas Review-Journal | LVR |
| Charleston Gazette | CG | The New York Times | NYT |
| Pittsburgh Post-Gazette | PPG | The Pantagraph | PG |
| Portland Press Herald | PPH | The Philadelphia Inquirer | PI |
| Sarasota Herald-Tribune | SHT | The Wall Street Journal | WSJ |
| St. Louis Post-Dispatch | SLP | The Washington Post | WP |
| Telegram & Gazette Worcester | TGW | USA Today | UT |
| The Boston Globe | BG | Winston-Salem Journal | WiSJ |
| The Evansville Courier | EC | | |

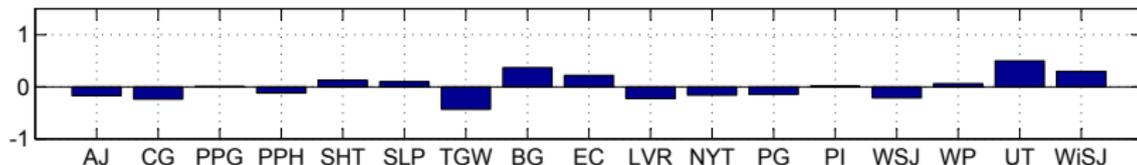
The Estimated News Topics

Specialization of Newspapers

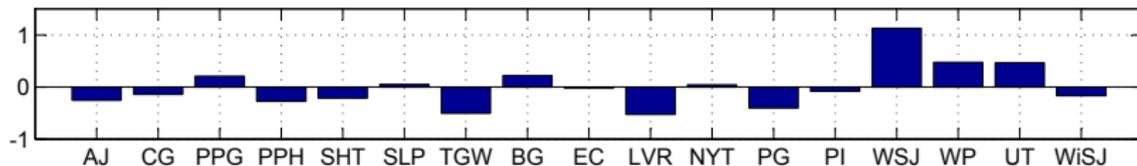
Topic 1: Afghanistan



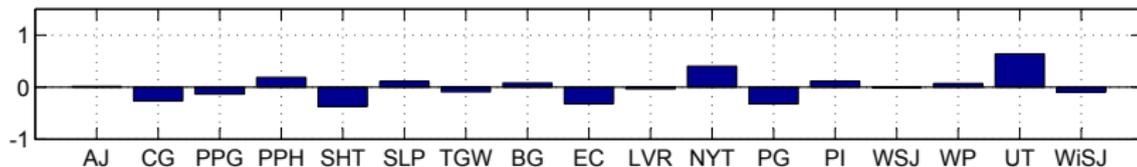
Topic 2: 2008 Presidential Candidate Conventions



Topic 5: Financial Crisis and Bailouts



Topic 9: Terror Attacks



Two Measures of News Coverage over Time

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1. **Fraction of total news** devoted to topic k on day t

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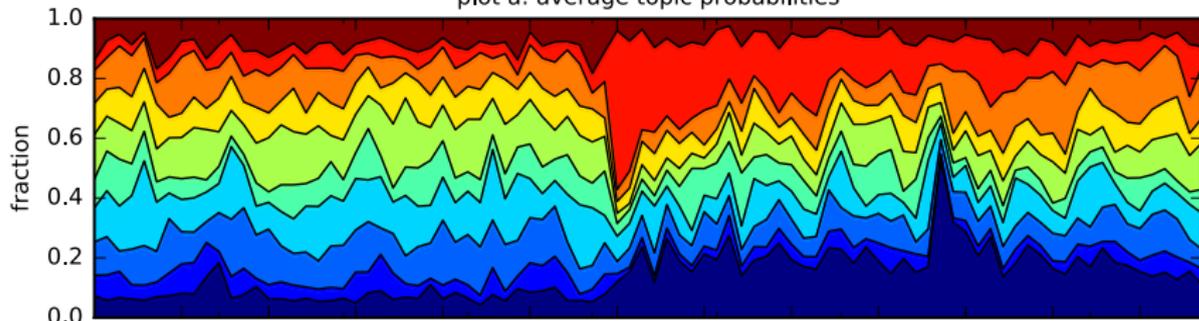
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2. **Homogeneity** of news coverage

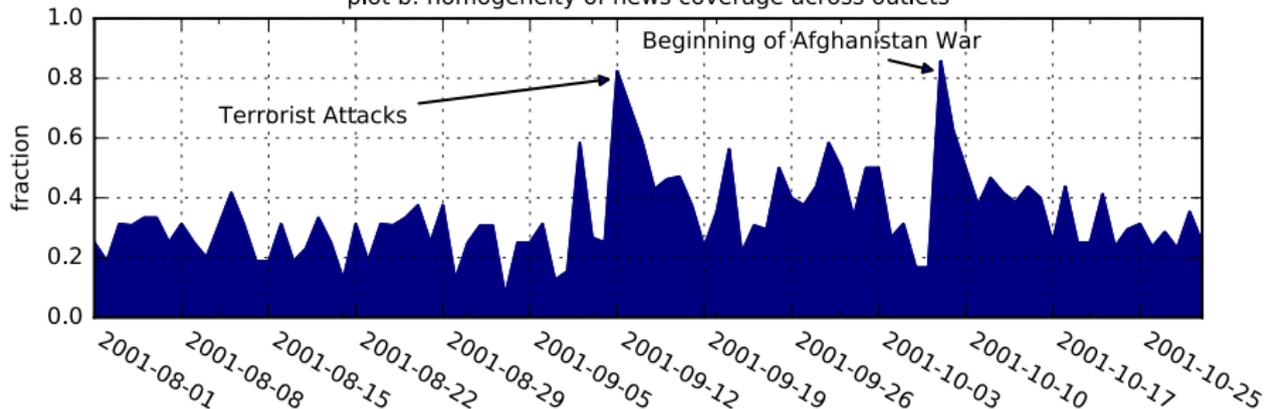
$$H_t \equiv \frac{\sum_m \mathcal{I}(\arg \max_k F_{t,m,k} = \arg \max_k F_{t,k})}{M}$$

Editorial Decisions around 9/11

plot a: average topic probabilities

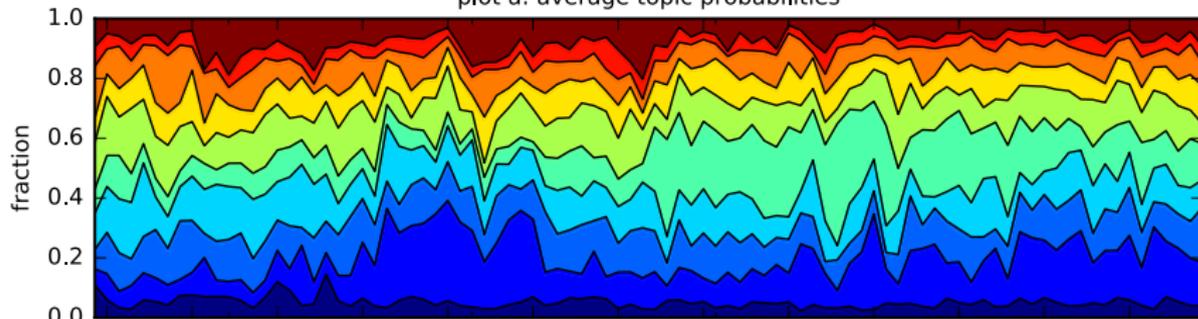


plot b: homogeneity of news coverage across outlets

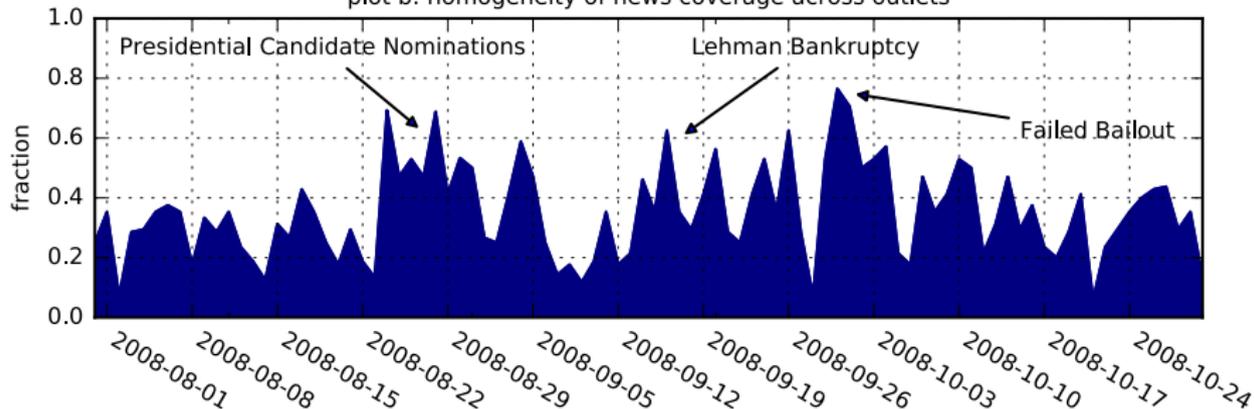


Editorial Decisions around Lehman Bankruptcy

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The model incorporates these features in as simple of a setup as possible

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- ▶ $S_i = 1$ means that Paper i reports X_i

Simple Discrete State Space Example

The Model with a Discrete State Space

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The potential stories X_a and X_b can take the values -1, 0, or 1 with probabilities given by:

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$$p_i(x_i | x_j) = p_i(x_i) : i \neq j, \in i, j \{a, b\}$$

Neither the symmetry nor the independence of the distributions for X_a and X_b are necessary

Equilibrium News Selection Functions

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News selection functions

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No strategic motive

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Paper A

| | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ |
|------------|------------|-----------|-----------|
| $X_b = -1$ | A | A | A |
| $X_b = 0$ | A | A | A |
| $X_b = 1$ | A | A | A |

Paper B

| | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ |
|------------|------------|-----------|-----------|
| $X_b = -1$ | B | B | B |
| $X_b = 0$ | B | B | B |
| $X_b = 1$ | B | B | B |

Equilibrium News Selection Functions

News selection functions

No strategic motive

| Paper A | | | | Paper B | | | |
|------------|------------|-----------|-----------|------------|------------|-----------|-----------|
| | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ | | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ |
| $X_b = -1$ | A | A | A | $X_b = -1$ | B | B | B |
| $X_b = 0$ | A | A | A | $X_b = 0$ | B | B | B |
| $X_b = 1$ | A | A | A | $X_b = 1$ | B | B | B |

Strategic motive ($\lambda \neq 0$)

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|------------|------------|-----------|-----------|------------|------------|-----------|-----------|
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| $X_b = 0$ | A | A | A | $X_b = 0$ | B | B | B |
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Strategic motive ($\lambda \neq 0$)

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Consider the state $(0, 1)$:

News selection function

Strategic motive ($\lambda \neq 0$)

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|------------|------------|-----------|-----------|------------|------------|-----------|-----------|
| | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ | | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ |
| $X_b = -1$ | A | B | A | $X_b = -1$ | B | B | B |
| $X_b = 0$ | A | A | A | $X_b = 0$ | A | B | A |
| $X_b = 1$ | A | B | A | $X_b = 1$ | B | B | B |

News Selection Functions and Beliefs

Because of news selection, even though agents read only one story, their beliefs about both stories are updated

Consider the state $(0, 1)$:

- ▶ Alice knows that $X_b = 1$

News selection function

Strategic motive ($\lambda \neq 0$)

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|------------|------------|-----------|-----------|
| | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ |
| $X_b = -1$ | A | B | A |
| $X_b = 0$ | A | A | A |
| $X_b = 1$ | A | B | A |

| | Paper B | | |
|------------|------------|-----------|-----------|
| | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ |
| $X_b = -1$ | B | B | B |
| $X_b = 0$ | A | B | A |
| $X_b = 1$ | B | B | B |

News Selection Functions and Beliefs

Because of news selection, even though agents read only one story, their beliefs about both stories are updated

Consider the state $(0, 1)$:

- ▶ Alice knows that $X_b = 1$
- ▶ But she also knows that $X_a = 0$, since in the states $(1, 1)$ and $(-1, 1)$ she would observe X_a

News selection function

Strategic motive ($\lambda \neq 0$)

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| $X_b = 0$ | A | A | A |
| $X_b = 1$ | A | B | A |

| | Paper B | | |
|------------|------------|-----------|-----------|
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News Selection Functions and Higher Order Beliefs

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|------------|------------|-----------|-----------|------------|------------|-----------|-----------|
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News Selection Functions and Higher Order Beliefs

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Consider the state $(1, 0)$:

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- ▶ Bob can infer with certainty that Alice also knows that $X_a = 1$

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News Selection Functions and Higher Order Beliefs

Some events are observed by both Alice and Bob, and yet the event may not be common knowledge

Consider the state $(1, 0)$:

- ▶ Both Alice and Bob know that $X_a = 1$
- ▶ Bob can infer with certainty that Alice also knows that $X_a = 1$
- ▶ Alice assigns probability $\frac{1}{2}$ to Bob knowing that $X_a = 1$

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| | Paper A | | | | Paper B | | |
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| | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ | | $X_a = -1$ | $X_a = 0$ | $X_a = 1$ |
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Actions and Common Information

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Alice's action when she observes X_a

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$$y_a(x_a) = (1 - \lambda)x_a + \lambda p(S_b = 0 \mid S_a = 1, x_a) y_b(x_a)$$

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$$y_a(x_a) = \frac{(1 - \lambda)}{1 - \frac{1}{2}\lambda^2}x_a, \quad y_b(x_a) = \lambda \frac{(1 - \lambda)}{1 - \frac{1}{2}\lambda^2}x_a$$

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The strength of the response of both agents depends on $p(S_b = 0 \mid S_a = 1, x_a)$.

Additional Results in Paper

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Delegated information choice introduces correlation in actions compared to ex ante signal choice model

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- ▶ Sign of correlation inherited from λ

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- ▶ Extreme events are closer to common knowledge

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- ▶ Sign of correlation inherited from λ

Continuous distributions

- ▶ Extreme events are closer to common knowledge
- ▶ The degree to which information about a given event is common depends on preferences and distributions

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We made strong assumptions regarding benevolence of news media

- ▶ Report events with perfect accuracy and select to maximize utility of readers
- ▶ As long as news selection is systematic and understood by the agents, the mechanism applies

Appendix

News Selection Functions and Beliefs

Proposition: Posterior beliefs about the unreported story X_j coincides with the prior distribution $p(x_j)$, i.e.

$$p(x_j | \mathcal{S}_i = 1, x_i) = p(x_j) \quad (1)$$

only if the probability of reporting x_i is conditionally independent of x_j

$$p(\mathcal{S}_i = 1 | x_i) = p(\mathcal{S}_i = 1 | x_j, x_i).$$

Proof: By Bayes' rule

$$p(x_j | \mathcal{S}_i = 1, x_i) = \frac{p(\mathcal{S}_i = 1 | x_j, x_i)}{p(\mathcal{S}_i = 1 | x_i)} p(x_j)$$

so that (1) holds only if

$$\frac{p(\mathcal{S}_i = 1 | x_j, x_i)}{p(\mathcal{S}_i = 1 | x_i)} = 1.$$

Delegated News Selection and Correlated Actions

Alternative Benchmark Model: Optimal Actions with Ex Ante Signal Choice

Agents subject to same constraint on number of stories but must choose *ex ante* which story to read about.

When $(1 - \lambda^2)^2 + \lambda > 0$

- ▶ Alice will choose to always observe X_a
- ▶ Bob will choose to always observe X_b .

Since

$$E[x_i | x_j] = 0 : i \neq j$$

the optimal action is given by

$$y_i = (1 - \lambda) x_i : i \in a, b$$

Alice and Bob's actions are uncorrelated if X_a and X_b are independent

News Selection and Correlation of Actions

Direct computation of the correlation of Alice and Bob's actions gives

$$\frac{\sum p(\omega) y_a(\omega) y_b(\omega)}{\sqrt{\text{var}(y_a)} \sqrt{\text{var}(y_b)}} = 2\lambda \frac{(1-\lambda)^2}{(2-\lambda^2)^2} \text{var}(y_i)^{-1}$$

- ▶ The terms in the sum associated with the states $(0, 1)$, $(0, -1)$, $(1, 0)$ and $(-1, 0)$ have the same sign as λ with delegated news selection
- ▶ The same terms are zero with ex ante information choice

Extreme Events

Extreme Events and Approximate Common Knowledge

The discrete, low dimensional set up does not lend itself to study large magnitude, or extreme, events

Continuous distributions of events allow us to think of how the magnitude of an event affect beliefs and actions

- ▶ $X_i \sim N(0, \frac{1}{3})$
- ▶ News selection parameterized a

$$S_i = \begin{cases} 1 & \text{if } |x_i| \geq \alpha |x_j|^\beta \\ 0 & \text{otherwise} \end{cases}$$

- ▶ Optimal actions

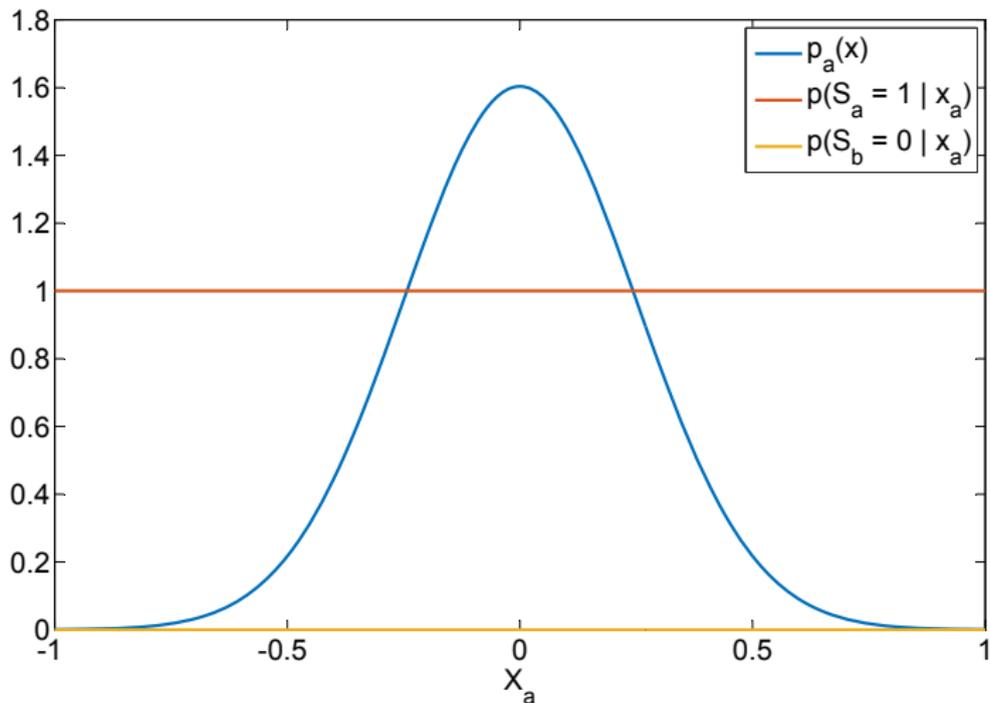
$$y_i(x_i) = \frac{(1 - \lambda)}{1 - \lambda^2 p(S_j = 0 \mid x_i, S_i = 1)} x_i$$

and

$$y_i(x_j) = \lambda \frac{(1 - \lambda)}{1 - \lambda^2 p(S_i = 0 \mid x_j, S_j = 1)} x_j$$

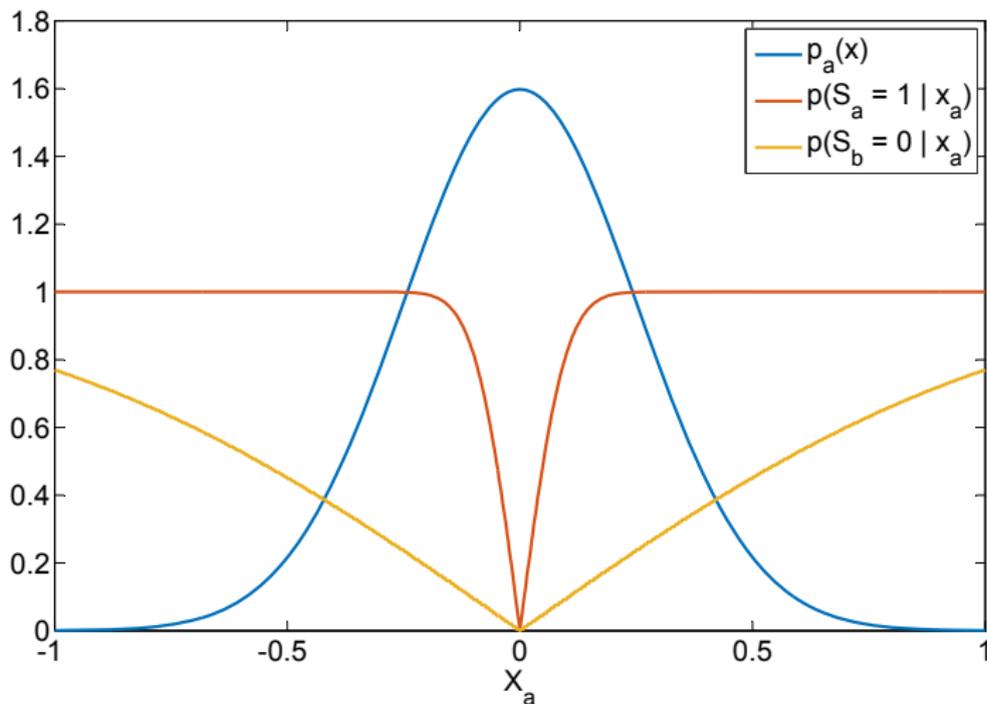
Extreme Events and Common Knowledge

$$\lambda = 0$$



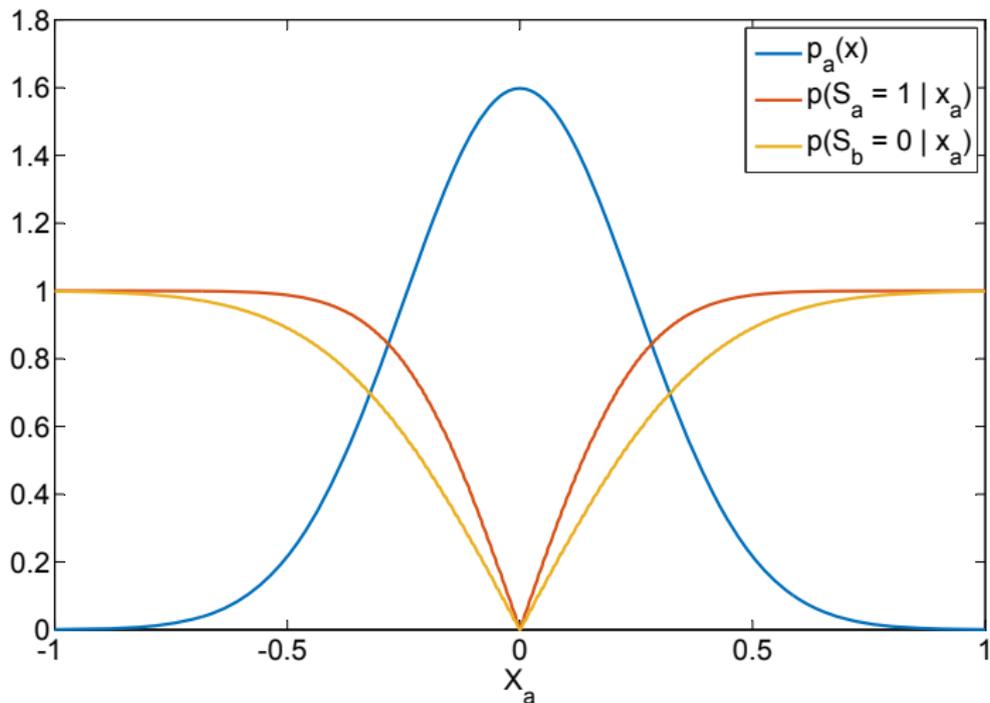
Extreme Events and Common Knowledge

$$\lambda = 0.3$$



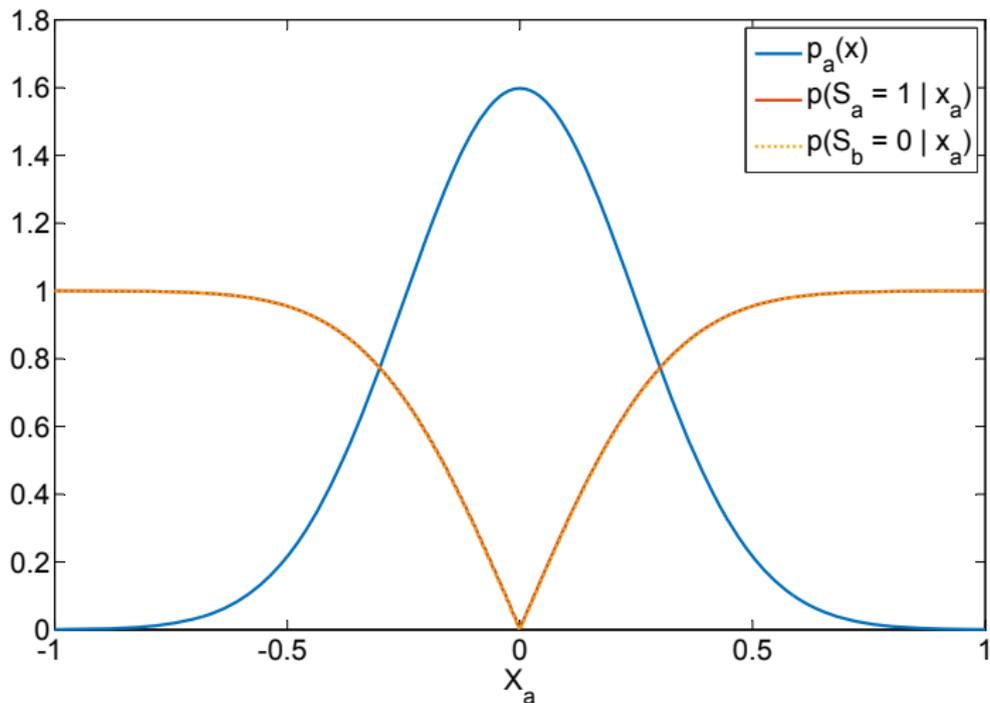
Extreme events and common knowledge

$$\lambda = 0.45$$

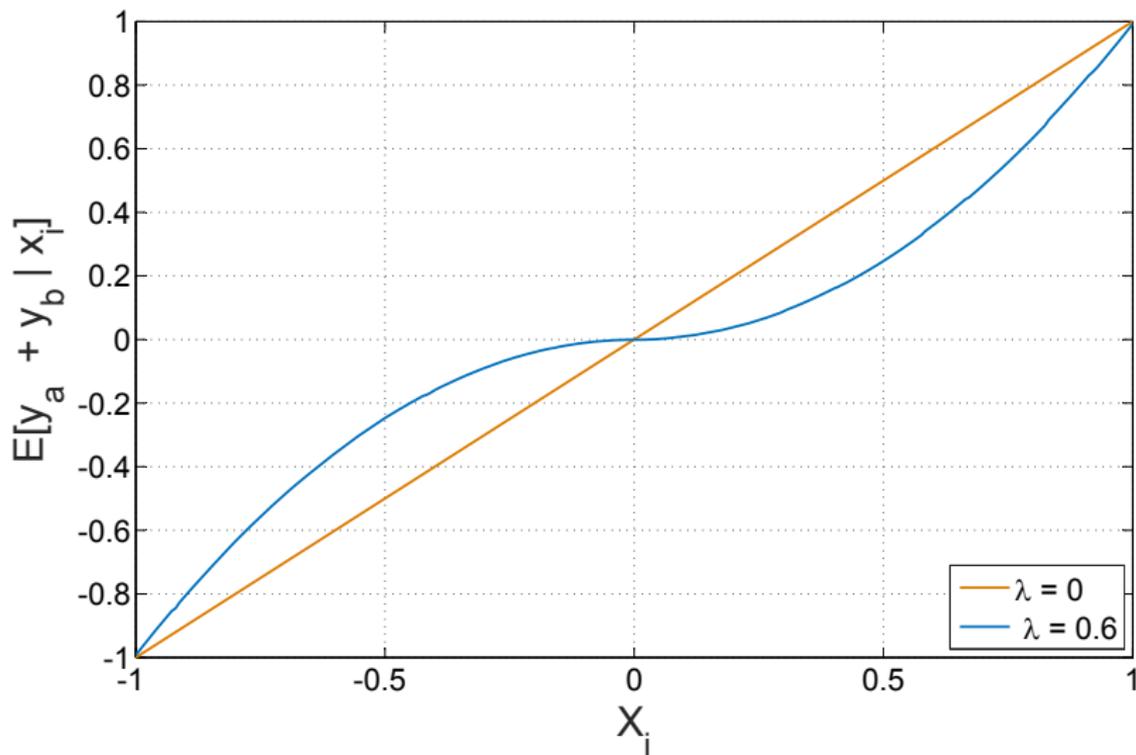


Extreme Events and Common Knowledge

$$\lambda = 0.6$$



Expected Aggregate Action



Estimating the LDA Model

The probability of a specific text corpus being generated is described by the distribution

$$p(\beta, \theta, z, w) = \prod_{i=1}^K p(\beta_i) \prod_{d=1}^D p(\theta_d) \left(\prod_{n=1}^N p(z_{d,n} | \theta_d) p(w_{d,n} | \beta_{1:K}, z_{d,n}) \right)$$

where β, θ and z are unobserved parameters and w is a vector space representation of the text corpus.

We want to form a posterior distribution for the latent parameters conditional on the observed text corpus

$$p(\beta, \theta, z | w) = \frac{p(\beta, \theta, z, w)}{p(w)}$$

We use Collapsed Gibbs Sampling algorithm of Griffiths and Steyvers (2004)