## Filtering with limited information

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## Lars Peter Hansen (2014)

Hansen (1982) builds on a long tradition in econometrics of 'doing something without having to do everything.' This entails the study of partially specified models, that is, models in which only a subset of economic relations are formally delineated.

## Motivation

- Filtering shocks from a dynamic model is a central task in macroeconomics:

1. Path of shocks is a reality check for the model.
2. Historical decompositions and counterfactuals.
3. Forecasting and optimal policy recommendations when laws of motions are state-dependent.
4. Structural estimation.

- However, filtering is hard, and there is no universal and easy-to-apply algorithm to implement it.


## Alternatives

- A possibility $\Rightarrow$ sequential Monte Carlos: Fernández-Villaverde, Rubio-Ramírez, and Schorfheide (2016).

1. Specification of the full model, including auxiliary assumptions.
2. Computationally costly.
3. Curse of dimensionality.

- Some of the previous points also hold for even the simple linear, Gaussian case where we can apply the Kalman filter.
- Can we follow Hansen's suggestion and 'do something without having to do everything" ? $\Rightarrow$ Yes!
- Partial information filter.


## Environment

- Model:

$$
f\left(x_{t}, y_{t}, \mathbb{E}_{t}\left[g\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)\right]\right)=\mathbf{0}
$$

- Deterministic steady state:

$$
f(\bar{x}, \bar{y}, g(\bar{x}, \bar{y}, \bar{x}, \bar{y})])=\mathbf{0}
$$

- Estimation:

$$
f\left(\widehat{x}_{t}, y_{t}, \widehat{\mathbb{E}}_{t}\left[g\left(\widehat{x}_{t+1}, y_{t+1}, \widehat{x}_{t}, y_{t}\right)\right]\right)=\mathbf{0}
$$

## Factorization

- Factorization of $g(\circ)$

$$
g\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right) \equiv g_{1}\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right) \times g_{2}\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)
$$

- Then:

$$
\begin{aligned}
\mathbb{E}_{t}\left[g\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)_{i}\right] \equiv & \mathbb{E}_{t}\left[g_{1}\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)_{i}\right] \times \mathbb{E}_{t}\left[g_{2}\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)_{i}\right] \\
& +\operatorname{Cov}_{t}\left[g_{1}\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)_{i}, g_{2}\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)_{i}\right]
\end{aligned}
$$

- We need to approximate conditional first and second moments:

1. Equilibrium conditions of the model.
2. Observed expectations.
3. Auxiliary statistical model.

## Auxiliary statistical model

- $\operatorname{VAR}(1)$ in $g_{1, t}, g_{2, t}$, (a subset of $n_{\tilde{y}}$ elements of) $y_{t}$, and $\widehat{x}_{t}$ for $t=1, \ldots, T$.
- Why?
- If we collect variables collected in $\xi_{t}$ :

$$
\xi_{t}=\mu+A \xi_{t-1}+\epsilon_{t}, \quad \operatorname{Var}\left[\epsilon_{t}\right]=\Sigma
$$

- Ordering $g_{1, t}$ and $g_{2, t}$ as the first two variables of the VAR, we can write:

$$
\mathbb{E}_{t}\left[g\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)\right]_{i} \equiv\left(\mu_{i}+e_{i}^{\prime} A \xi_{t}\right)\left(\mu_{i+m}+e_{i+m}^{\prime} A \xi_{t}\right)+\Sigma_{i, i+m}
$$

where $e_{i}$ is a selection vector.

- Thus:

$$
f\left(x_{t}, y_{t},\left(\mu_{i}+e_{i}^{\prime} A \xi_{t}\right)\left(\mu_{i+m}+e_{i+m}^{\prime} A \xi_{t}\right)+\Sigma_{i, i+m}\right)_{i}=0
$$

## Two approaches

- (Fixed point): we find $\widehat{x}^{\top}$ (and associated parameters for the VAR) that solve for all $i$ :

$$
f\left(x_{t}, y_{t},\left(\mu_{i}+e_{i}^{\prime} A \xi_{t}\right)\left(\mu_{i+m}+e_{i+m}^{\prime} A \xi_{t}\right)+\Sigma_{i, i+m}\right)_{i}=0
$$

In practice, initialize $\widehat{E}_{t}^{(0)}[g(\circ)]$ based on $\widehat{x}_{t}^{(0)}=\bar{x} \forall t$ and $A^{(0)}=\mathbf{0}, \mu^{(0)}=\bar{\xi}_{T}$ and $\Sigma^{(0)}=\mathbf{0}$ and iterate until convergence.

- (Gibbs sampler): From $d=1, \ldots, D$, iterate on:

1. Given $\left\{\hat{X}_{t}^{(d)}\right\}_{t=1}^{T}, \mu^{(d)}, A^{(d)}, \Sigma^{(d)} \sim P\left(\mu, A, \Sigma \mid \xi_{t}\right)$.
2. Given $y^{\top}, \mu^{(d)}, A^{(d)}, \Sigma^{(d)}$, solve for $\left\{\hat{\mathrm{x}}_{t}^{(d+1)}\right\}_{t=1}^{T}$ for all $i$ in:

$$
f\left(x_{t}, y_{t},\left(\mu_{i}+e_{i}^{\prime} A \xi_{t}\right)\left(\mu_{i+m}+e_{i+m}^{\prime} A \xi_{t}\right)+\Sigma_{i, i+m}\right)_{i}=0
$$

Start the Gibbs sampler from $\widehat{x}_{t}^{(0)}=\bar{x}$ or the fixed point above.
The Gibbs sampler allows us to quantify estimation uncertainty.

## Tobin's Q

- Representative household

$$
\begin{gathered}
\max _{\left\{c_{t}, n_{t}, i_{t}\right\}} \mathbb{E} \sum_{s=0}^{\infty}\left(\prod_{u=1}^{s} \beta_{t-1+s}\right) u\left(c_{t+s}, n_{t+s}\right) \\
\text { s.t. } \\
k_{t+1}=\left(1-\delta_{t}\right) k_{t}+e^{\xi_{t}}\left(1-\frac{\chi}{2}\left(\frac{i_{t}}{i_{t-1}}-(1+g)\right)^{2}\right) i_{t} \\
c_{t}+i_{t}=e^{z_{t}} k_{t-1}^{\alpha} n_{t}^{1-\alpha}
\end{gathered}
$$

- Four shocks: $\beta_{t}, \delta_{t}, \xi_{t}, z_{t}$ follow log-linear $\operatorname{AR}(1)$ processes


## Solution (I)

$$
\begin{gathered}
c_{t}^{-\eta}\left(1-\kappa(1-\eta) n_{t}^{1+1 / \phi}\right)^{1-\eta}=\lambda_{t} \\
c_{t}^{1-\eta}\left(1-\kappa(1-\eta) n_{t}^{1+1 / \phi}\right)^{-\eta}(1+1 / \phi) \kappa(1-\eta) n_{t}^{1 / \phi}=\lambda_{t}(1-\alpha) e^{z_{t}}\left(\frac{k_{t-1}}{n_{t}}\right)^{\alpha} \\
\lambda_{t}=\mu_{t} e^{\xi_{t}}\left(1-\frac{\chi}{2}\left(\frac{i_{t}}{i_{t-1}}-(1+g)\right)^{2}-\chi\left(\frac{i_{t}}{i_{t-1}}-(1+g)\right) \frac{i_{t}}{i_{t-1}}\right) \\
+\beta_{t} \mathbb{E}_{t}\left[\mu_{t+1} \chi\left(\frac{i_{t+1}}{i_{t}}-(1+g)\right)\left(\frac{i_{t+1}}{i_{t}}\right)^{2}\right] \\
\mu_{t}=\beta_{t} \mathbb{E}_{t}\left[\left(1-\delta_{t+1}\right) \mu_{t+1}+\lambda_{t+1} \alpha e^{z_{t+1}}\left(\frac{n_{t+1}}{k_{t}}\right)^{1-\alpha}\right]
\end{gathered}
$$

## Solution (II)

$$
\begin{gathered}
c_{t}^{-\eta}\left(1-\kappa(1-\eta) n_{t}^{1+1 / \phi}\right)^{1-\eta}=\lambda_{t} \\
c_{t}^{1-\eta}\left(1-\kappa(1-\eta) n_{t}^{1+1 / \phi}\right)^{-\eta}(1+1 / \phi) \kappa(1-\eta) n_{t}^{1 / \phi}=\lambda_{t}(1-\alpha) e^{z_{t}}\left(\frac{k_{t-1}}{n_{t}}\right)^{\alpha} \\
1=q_{t} e^{\xi_{t}}\left(1-\frac{\chi}{2}\left(\frac{i_{t}}{i_{t-1}}-(1+g)\right)^{2}-\chi\left(\frac{i_{t}}{i_{t-1}}-(1+g)\right) \frac{i_{t}}{i_{t-1}}\right) \\
+\mathbb{E}_{t}\left[\beta_{t} \frac{\lambda_{t+1}}{\lambda_{t}} q_{t+1} \chi\left(\frac{i_{t+1}}{i_{t}}-(1+g)\right)\left(\frac{i_{t+1}}{i_{t}}\right)^{2}\right] \\
q_{t}=\mathbb{E}_{t}\left[\beta_{t} \frac{\lambda_{t+1}}{\lambda_{t}}\left(\left(1-\delta_{t+1}\right) q_{t+1}+r_{t+1}^{k}\right)\right]
\end{gathered}
$$

where $r_{t}^{k} \equiv \alpha e^{z_{t+1}}\left(\frac{n_{t+1}}{k_{t}}\right)^{1-\alpha}$

## Quantitative set-up

- Calibration:

1. $\bar{n}=\frac{1}{3}$.
2. $\bar{g}=0.5 \%$, a $2 \%$ annual growth rate.
3. $\eta=1.0$, to have separable preferences for now.
4. $\phi=1$, a typical value for the Frisch elasticity.
5. $\bar{\delta}=2 \%$, implying an $8 \%$ annual depreciation rate.
6. $\beta=0.995$, implying a annualized real rate of about $2 \%+4 \eta \bar{g}=5 \%$.
7. $\rho_{z}=0.95, \sigma_{z}=0.76 \%$.
8. $\rho_{\beta}=0.8, \sigma_{\beta}=1.0 \%$.
9. $\rho_{\xi}=0.9, \sigma_{\xi}=1.0 \%$.
10. $\rho_{\delta}=0.75, \sigma_{\delta}=1.0 \%$.

- Solved the model using 3rd order perturbation methods with pruning, as in Andreasen, Fernández-Villaverde, and Rubio Ramírez (2017).
- Simulated data: We simulate the model for 2,000 periods after a burn-in of 1,000 periods.


## Filter set up

- We want to filter a single variable, $q_{t}$ using data on the SDF $M_{t+1} \equiv \beta_{t} \frac{\lambda_{t+1}}{\lambda_{t}}$, the rental rate on capital $r_{t}^{k}$, and the risk-free rate $r_{t}^{f}$.
- Set $x_{t}=q_{t}, y_{t}=\left[\tilde{M}_{t}, r_{t}^{k}, r_{t}^{f}\right]$, and rewrite the conditional expectation of the return on investment as:

$$
\begin{aligned}
g\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right) & \equiv y_{1, t+1} \times\left((1-\bar{\delta}) x_{t+1}+y_{2, t+1}\right) \\
& =\widetilde{M}_{t+1} \times\left((1-\bar{\delta}) q_{t+1}+r_{t+1}^{k}\right)
\end{aligned}
$$

with $\widetilde{M}_{t+1}=\bar{\beta} \frac{c_{t}}{c_{t+1}}$.

- Note use of misspecified model.
- Thus

$$
\begin{aligned}
f\left(x_{t}, y_{t}, \mathbb{E}_{t}\left[g\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right]\right)\right. & \equiv-x_{t}+\mathbb{E}_{t}\left[g\left(x_{t+1}, y_{t+1}, x_{t}, y_{t}\right)\right] \\
& =-q_{t}+\mathbb{E}_{t}\left[\widetilde{M}_{t+1} \times\left((1-\bar{\delta}) q_{t+1}+r_{t+1}^{k}\right)\right]
\end{aligned}
$$

## Auxiliary statistical model

- Using that, in equilibrium, $1+r_{t}^{f} \equiv \mathbb{E}_{t}\left[M_{t+1}\right]^{-1}$, we can re-write previous expression as an VAR approximation:

$$
\begin{gathered}
f\left(x_{t}^{(d)}, y_{t}, \widehat{\mathbb{E}}_{t}^{(d)}\left[g\left(x_{t+1}^{(d-1)}, y_{t+1}, x_{t}^{(d-1)}, y_{t}\right]\right) \approx\right. \\
-x_{t}^{(d-1)}+(1-\bar{\delta}) \Sigma_{1,4}^{(d)}+\Sigma_{1,2}^{(d)} \\
+\left(1+r_{t}^{f}\right)^{-1} \times\left((1-\bar{\delta}) e_{4}+e_{1}\right)\left(\mu^{(d)}+A^{(d)} X_{t}^{(d-1)}\right)
\end{gathered}
$$

- We already are setting up notation for Gibbs sampler.
- For comparison purposes, we will also run:

1. A naive guess for $q$ computed as $q_{t}=\frac{(1-\bar{\delta})+m p k_{t+1}}{1+r_{t}^{t}}$.
2. A Kalman filter and smoother.

## VAR

- $\operatorname{VAR}(1)$ in $\xi_{t}^{(d)} \equiv\left[M_{t+1}, r_{t+1}^{k}, r_{t+1}^{f}, \widehat{q}_{t}^{(d)}\right]:$

1. Fixed point: We solve for a fixed point in the 2,000-dimensional vector $\widehat{q}^{(f p), T}$ and the VAR parameters $\widehat{\mu}^{(f p)}, A^{(f p)}$, and $\Sigma^{(f p)}$.
2. Gibbs sampler:
2.1 Set $\xi_{0}^{(d)}=\left[M_{0}, r_{0}^{k}, r_{0}^{f}, \bar{q}\right]$
2.2 We sample
$\Sigma^{(d)}$ and $\beta^{(d)}=\left[\operatorname{vec}\left(A^{(d)}\right)^{\prime},\left(\mu^{(d)}\right)^{\prime}\right]^{\prime}$
from
$\Sigma^{(d)} \mid \xi^{(d), T} \sim \mathcal{I W}\left(T-1, \widehat{\Sigma}_{O L S}^{(d)} \times T\right)$
and
$\beta^{(d)} \mid \xi^{(d), T}, \Sigma^{(d)} \sim \mathcal{N}\left(\widehat{\beta}_{O L S}^{(d)}, \Sigma^{(d)} \otimes\left(\left(\bar{\xi}^{(d-1)}\right)^{\prime} \bar{\xi}^{(d-1)}\right)^{-1}\right)$, conditioning on $\xi_{0}^{(d)}=\left[M_{0}, r_{0}^{k}, r_{0}^{f}, \bar{q}\right]$.
2.3 We use a flat prior and define $\hat{\Sigma}_{O L S}^{(d)} \times T$ as the OLS sum of squared residuals and $\widehat{\beta}_{O L S}^{(d)}$ the OLS estimator/MLE of the coefficients. $\bar{\xi}$ is a $T \times 5$ matrix with rows $\bar{\xi}_{t}=\left[\xi_{t-1}, 1\right]$.
2.4 We solve optimality condition for $\widehat{q}_{t}^{(d)}$.





## Political distribution risk and aggregate fluctuations

## Budd (2012), 'Labor Relations - Striking a Balance,' 4th ed.

A popular framework for thinking about labor law is to consider a pendulum that can range from strong bargaining power for labor ... to strong bargaining power for companies

We stress the role that changes in

1. statutory labor law (including executive orders),
2. case law (courts and NLRB), and
3. political climate
have on business cycles, income shares, and asset prices.

## Model

- RBC model with search and matching frictions. (Andolfatto, 1996; Merz, 1995; Shimer, 2010)
- Household with a continuum of members. Members are either employed or unemployed.
- Household insures members against idiosyncratic employment risk.
- Competitive firms that choose recruiting intensity.
- Government.
- Complete markets.
- Bargaining power subject to persistent redistribution shocks.


## Households

- Recursive problem of the head of household:

$$
V\left(a, n_{-1}\right)=\max _{a^{\prime}, n, c} \frac{c^{1-\sigma}\left(1+(\sigma-1) \gamma n_{-1}\right)^{\sigma}-1}{1-\sigma}+\beta \mathbb{E}\left[V\left(a^{\prime}, n\right)\right]
$$

with

$$
c \equiv c_{e} n_{-1}+c_{u}\left(1-n_{-1}\right)
$$

- Budget constraint:

$$
c+\mathbb{E}\left[m^{\prime} * a^{\prime}\right]=\left(1-\tau_{n}\right) w n_{-1}+T+a
$$

with stochastic discount factor $m$.

- Law of motion of employment:

$$
n=(1-x) n_{-1}+f(\theta)\left(1-n_{-1}\right),
$$

with job finding rate $f(\theta)=\xi \theta^{\eta}$.

## Firms

- Firm produces output $y$ using effective capital $u k_{-1}$ and production workers $(1-\nu) n_{-1}$ :

$$
y=\left(\alpha^{\frac{1}{\varepsilon}}\left(u k_{-1}\right)^{1-\frac{1}{\varepsilon}}+(1-\alpha)^{\frac{1}{\varepsilon}}\left(z(1-\nu) n_{-1}\right)^{1-\frac{1}{\varepsilon}}\right)^{\frac{\varepsilon}{\varepsilon-1}},
$$

Fraction $\nu$ workers devoted to recruiting activities.

- Laws of motion for employment and capital:

$$
\begin{aligned}
& n=n_{-1}(\nu \mu(\theta)+1-x) \\
& k=(1-\delta(u)) k_{-1}+I\left(1-\frac{1}{2} \kappa\left(\frac{1}{k_{-1}}-\tilde{\delta}\right)^{2}\right)
\end{aligned}
$$

where $\mu(\theta)=f(\theta) / \theta$ is hiring probability per recruiter.

- Firm value:

$$
J\left(n_{-1}, k_{-1}\right)=\max _{n, k, \nu}\left(1-\tau_{k}\right)\left(y-w n_{-1}\right)-I+\tau_{k} \delta(\bar{u}) k_{-1}+\mathbb{E}\left[m^{\prime} * J(n, k)\right]
$$

## Wage determination

- Generalized Nash bargaining between firms and households.
- Workers have bargaining power $\phi$.
- Exogenous shifts in $\phi$ capture political shocks to bargaining process (Binmore et al., 1986).
- Other bargaining protocols? (Hall and Milgrom, 2008).
- Equilibrium wage solves

$$
w=\arg \max _{\tilde{w}} \tilde{V}_{n}(\tilde{w})^{\phi} \tilde{J}_{n}(\tilde{w})^{1-\phi}
$$

where $\tilde{V}_{n}$ and $\tilde{J}_{n}$ are marginal values of employment for households and firms given an arbitrary wage $\tilde{w}$.

- Equilibrium wage along the balanced growth path:

$$
\bar{w}=\bar{\phi} \times(1+\bar{\theta}) \overline{m p l}+(1-\bar{\phi}) \times \frac{\sigma}{1-\tau_{n}}\left(\frac{\gamma \bar{c}}{1+(\sigma-1) \gamma \bar{n}}\right) .
$$

## Equilibrium

- Government.
- Standard competitive equilibrium definition.
- Market clearing $y=c+I$.
- Aggregate capital and employment follow their law of motion.
- Two exogenous $\operatorname{AR}(1)$ shocks:

1. Labor productivity $z_{t}$.
2. Bargaining power $\ln \frac{\phi_{t}}{1-\phi_{t}}$ :
2.1 Baseline: half-life shocks of 8.5 years $\approx$ average control of
presidency/house/senate after WWII.
2.2 Middle-run: half-life shocks of 20 years $\approx$ medium-term in Comín and Gertler (2006).
2.3 Short run: half-life of 3.5 months.
2.4 Long-run: new steady state.

## Identification (I)

Higher bargaining power


Lower productivity


## Identification (II)



Lower productivity


## Identification (III)



Cyclicality of wages


## Identification (IV)

Relative volatility of investment


Cyclicality of wages


## Moment matching (I)

- Solve using pruned 3rd-order approximation (Andreasen et al., 2017).
- Select $\beta, \delta_{0}, \alpha$, and $\tau_{k}$ to match moments from corporate non-financial business sector:

1. $31.2 \%$ gross capital share
2. $12.7 \%$ gross depreciation share.
3. $29.9 \%$ share of taxes in net surplus.
4. 2.3 annual $\mathrm{K} / \mathrm{Y}$ ratio.

- Match labor market statistics following Shimer (2010).
- Parametrized productivity and bargaining power process to match:

1. $1.6 \%$ annual labor productivity growth.
2. Volatility of measured z given persistence $0.95^{1 / 3}$.
3. Cyclicality of wages.
4. Relative standard deviation of investment I relative to $Y$.

## Moment matching (II)

| Parameter | Value |  |
| :--- | :---: | :--- |
| Risk aversion $\sigma$ | 2 | Consumption of unemployed |
| Discount factor $\beta$ | $0.976^{1 / 12}$ | Corp. non-financial sector |
| Disutility of working $\gamma$ | such that $\bar{n}=0.95$ | $5 \%$ unemployment rate |
| Capital share $\alpha$ | 0.31 | Corp. non-financial sector |
| Elasticity of substitution $\varepsilon$ | 1 | Cobb-Douglas |
| Depreciation $\delta_{0}$ | $5.5 \% / 12$ | Corp. non-financial sector |
| Trend productivity growth $g_{z}$ | $1.016^{1 / 12}$ | Cooley and Prescott '95 |
| Inv. adj. cost $\kappa$ | $0.0575 \times\left(\delta_{0}\right)^{-2}$ | Rel. volatility of I |
| Capacity util. cost $\delta_{1}$ | such that $\bar{u}=1$ | Normalization |
| Capacity util. cost $\delta_{2}$ | $2 \delta_{1}$ | BGP ela. w.r.t. $\frac{m p k_{t}}{u_{t}}$ of $\frac{1}{2}$ |
| Separation rate $x$ | $3.3 \%$ | Shimer '05 |
| Bargaining power $\bar{\phi}$ | 0.5 |  |
| Matching elasticity $\eta$ | 0.5 |  |
| Matching efficiency $\bar{\mu}$ | $2.3(\mu(\bar{\theta})=8.4)$ | Recruiting efficiency |
| Income tax rate $\tau_{n}$ | 0.4 | Prescott '04 |
| Corporate tax rate $\tau_{k}$ | 0.3 | Corp. non-financial sector |
| Productivity persistence $\rho_{z}$ | $0.95^{1 / 3}$ | Cooley and Prescott '95 |
| Productivity s.d. $\omega_{z}$ | $0.76 \%$ | z volatility |
| Barg. power persistence $\rho_{\phi}$ | $0.98^{1 / 3}$ | 8 year half-life |
| Bargaining power s.d. $\omega_{\phi}$ | $27.75 \%$ | Wage cyclicality |

## Implementation of the partial filter

- Bargaining power enters only wage-setting.
- Wage-setting equation implies:

$$
\begin{aligned}
& e^{\ln \frac{\phi_{t}}{1-\phi_{t}}}\left(\left(m p l_{t}\left(1+\frac{1-x}{\left.\mu\left(\theta_{t}\right)\right)}\right)-w_{t}\right)\right. \\
& \left.-\left(1-x-f_{t}\left(\theta_{t}\right)\right) e^{\kappa_{\phi}+\left(\rho_{\phi}-1\right) \ln \frac{\phi_{t}}{1-\phi_{t}}+\frac{1}{2} \omega_{\phi}^{2}}\left(\operatorname{Cov}_{t}[\rho]+\frac{m p l_{t}}{\mu\left(\theta_{t}\right)}\right)\right) \\
= & w_{t}-\frac{1}{1-\tau_{n}}\left(\frac{c_{t}}{1+(\sigma-1) \gamma n_{t-1}}\right) \gamma \sigma, \quad \text { where } \\
\operatorname{Cov}_{t}[0] & =\operatorname{Cov}_{t}\left[\ln \frac{\phi_{t}}{1-\phi_{t}}, m_{t+1}\left(m p I_{t+1}\left(1+\frac{1-x}{\mu\left(\theta_{t+1}\right)}\right)-w_{t+1}\right)\right] .
\end{aligned}
$$

- Given $\operatorname{Cov}_{t}$, solve for $\ln \frac{\phi_{t}}{1-\phi_{t}}$. Iterate in Gibbs-Sampler.



## Concluding remarks

- We have other implementations.
- For example: sticky leverage of Gomes, Jermann, and Schmid (2016).
- However, many things to do:

1. Embedding the model in an RBC model could aid in the calibration.
2. Can we use machine-learning tools to improve the covariance/expectations computation?
3. Heterogeneous agent model.
4. Small sample results.
5. Role for state smoothing due to estimation uncertainty/approximation error.
