

Credit Conditions and the Effects of Economic Shocks: Amplification and Asymmetries*

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Abstract

In this paper we address three empirical questions related to credit conditions. Do they change the dynamic interactions of economic variables by characterizing different regimes? Do they amplify the effects of economic shocks? Do they generate asymmetries in the effects of economic shocks depending on the size and sign of the shock? To answer these questions, we introduce endogenous regime switching in the parameters of a large Multivariate Autoregressive Index (MAI) model, where all variables react to a set of observable common factors. We develop Bayesian estimation methods and show how to compute responses to common structural shocks. We find that credit conditions do act as a trigger variable for regime changes. Moreover, demand and supply shocks are amplified when they hit the economy during periods of credit stress. Finally, good shocks seem to have more positive effects during stress time, in particular on unemployment.

Keywords: Credit conditions, shock amplification, asymmetric effects, Multivariate Autoregressive Index models, Smooth Transition, Bayesian VARs, Large datasets, Structural Analysis.

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1 Introduction

There is by now substantial empirical evidence on the interaction of credit conditions and the macroeconomy. Several recent studies focused on corporate bond spreads, which tend to widen in stress periods, e.g., Gilchrist and Zakrajsek (2012), Faust, Gilchrist, Wright and Zakrajsek (2013) and Lopez-Salido, Stein and Zakrajsek (2017). A common result is that an increase in credit spreads leads to a decline in economic activity, e.g., Gilchrist, Yankov and Zakrajsek (2009). Lopez-Salido et al. (2017) describe how mean reversion in credit spreads due to sentiment implies that low credit spreads are followed two years later by widening spreads and a decline of economic activity. These empirical links between credit spreads and economic activity are supported by theoretical results, often presented in the context of DSGE models with financial frictions (Bernanke and Gertler, 1989; Kiyotaki and Moore, 1997; He and Krishnamurthy, 2013). Krishnamurthy and Muir (2017) argue that theoretical models describe financial crises, which lead to deep recessions, as the result of a negative sizeable financial shock affecting a fragile financial sector that leads to amplification of the initial shock. The implication for empirical analysis, as also suggested by Barnichon, Matthes and Ziegenbein (2017), is that shocks may have different effects depending on their size (large vs small), sign (positive vs negative) and the conditions on the financial sector.

Our paper contributes to the empirical literature. Specifically, we address three questions related to credit conditions. First, do they change the dynamic interactions of economic variables by characterizing different regimes? Second, do they amplify the effects of economic shocks? Third, do they generate asymmetries in the effects of economic shocks depending on the size and sign of the shock?

From an econometric point of view, to answer these questions we develop a particular Smooth Transition Vector Autoregressive (ST-VAR) model, which is simple, intuitive and computationally feasible. Parameters changes in a ST-VAR can be led either by an observable indicator (Weise, 1999), a combination of indicators (Galvao and Marcellino, 2014), or an unobserved factor (Galvao and Owyang, 2017). ST-VAR models have been often used to study asymmetries in the responses to monetary policy shocks (Weise, 1999), fiscal shocks (Auerback and Gorodnichenko, 2012) and financial shocks (Galvao and Owyang, 2017). ST-VAR models nest Threshold VAR models, where parameter time variation is abrupt, which were applied, e.g., by Balke (2000) to consider credit as a nonlinear propagator of shocks. In comparison with the nonlinear projection approach in Barnichon et al. (2017) that uses the sign of past

structural shocks to describe changes in the shock transmission, ST-VAR models employ a set of observed endogenous variables to characterize regime changes, implying that the regime may change endogenously as response to shocks.

ST-VAR models are normally estimated for a small set of endogenous variables (the examples above and others in the literature consider up to 5 variables) because the characterization of the regime-dependent dynamics worsens usual dimensionality issues in VAR models (see, e.g., the recent survey by Hubrich and Terasvirta (2013)). However, larger VARs are typically needed to obtain reliable estimates of responses to shocks (Bańbura, Giannone and Reichlin, 2010; Giannone, Lenza and Primiceri, 2015; Brunnermeier, Palia, Sastry and Sims, 2017). Moreover, the measurement of credit conditions is normally based on information from many different credit spreads, e.g., Hatzius, Hooper, Mishkin, Schoenholtz and Watson (2010). Gilchrist et al. (2009) and Galvao and Owyang (2017) employ factor augmented VAR models to deal with this dimensionality issue. We, instead, employ a novel approach that has many advantages when performing structural analysis, since it has no unobservable variables, there is only a small set of common shocks, and it can be easily extended to allow for regime changes.

We start from the Multivariate Autoregressive Index (MAI) model of Reinsel (1983). As argued by Carriero, Kapetanios and Marcellino (2016), MAI models are a special case of reduced-rank VAR models that are suitable for analyzing the effects of common structural shocks. The reduced-rank restrictions imposed on the matrices of the original VAR model imply that each variable is driven by (the lags of) a limited set of linear combinations of all variables, which can be interpreted as observable factors (indices). In this sense, MAI models are a bridge between VAR and factor-augmented VAR models with the advantage that the factors can be consistently estimated even if the number of variables is finite.

We introduce smooth transition regime changes in the parameters of the conditional mean and the conditional variance of the MAI model, with one of the observable common factors (specific linear combinations of economic variables) employed as transition variable. Hence, factors are not only the common drivers of all the variables, but also the triggers of parameter regime changes.

We develop Metropolis-in-Gibbs algorithms to estimate the smooth transition MAI (ST-MAI) model. We follow Lopes and Salazar (2005) and Galvao and Owyang (2017) to draw parameters of smooth transition function jointly in a Metropolis step. For the regime-conditional variance-covariance matrix, we use a variation of the inverse-Wishart proposal approach in Gal-

vao and Owyang (2017). We use the method proposed by Carriero, Kapetanios and Marcellino (2016) to estimate factors' loadings. Because the variance-covariance matrix changes with the regime, we use the triangularization method proposed by Carriero, Clark and Marcellino (2016) to further reduce the computational time caused by the large number of endogenous variables.

We apply the ST-MAI model to a set of 20 economic and financial variables, including indicators of economic activity, prices, interest rates and credit spreads. We use four factors: real, nominal, monetary and credit. We use the Bayesian Information Criterion (BIC) to compare ST-MAI specifications with each of these four factors as transition variable. The BIC clearly selects the credit factor as the trigger of regime changes. In the resulting model, the threshold for low/high stress periods is endogenously determined, as well as the timing of the regimes (in contrast to Aikman, Lehner, Liang and Modugno (2017)). The identified periods of low/high stress are in line with common wisdom and are correlated but do not perfectly overlap with the NBER business cycle chronology. Hence, to answer our first question, we do find that credit conditions change the dynamic interactions of economic variables.

Using the selected large ST-MAI model with the credit factor as transition variable, we then compute (generalized) impulse response functions to demand, supply, monetary and credit shocks. We find that shocks that depress economic activity (negative demand shocks and positive supply shocks) are amplified when they hit the economy in the credit stress regime. Similarly, shocks that widen credit spreads have amplified negative effects on prices when the economy is in the credit stress regime. Hence, to answer our second question, we find substantial evidence that credit conditions can amplify the effects of economic shocks.

Finally, and in contrast to Lopez-Salido et al. (2017) who found no asymmetric effects of changes in credit spreads on GDP growth, we find that unemployment responds differently to positive and negative shocks and to large and small shocks when the model is in the credit stress regime. Shocks that decrease either the policy rate, prices or credit spreads have faster and stronger effects on unemployment than shocks that increase these variables. And, if these shocks are large, they have disproportionate larger effects on unemployment and the policy rate if they hit the economy in a period of credit stress. Hence, to answer our third question, we also find evidence that credit conditions can trigger asymmetric effects of economic shocks. Shocks can have asymmetric effects in the ST-MAI model because they can change the probability of regime changes, as the variables that underlie changes are endogenous in the model.

The remaining of the paper is organized as follows. Section 2 reviews the MAI model and

then introduces the ST-MAI model. It also outlines the Bayesian estimation strategy, the shock identification approach, and a method for computation of the impulse responses. Section 3 applies the ST-MAI model to address our three empirical research questions. It also presents results from a small ST-VAR model to show the relevance of using a larger information set for structural analysis in order to alleviate omitted variable problems. Section 4 summarizes and concludes.

2 The Smooth Transition Multivariate Autoregressive Index Model

This section presents the Smooth Transition Multivariate Autoregressive Index (ST-MAI) model, to be used to study amplification and asymmetries in the effects of economic shocks depending on credit conditions. After introducing the model, we consider (Bayesian) estimation, specification issues, and computation of impulse responses to (common) structural shocks,

2.1 The ST-MAI model

Let us assume that an $N \times 1$ vector of variables Y_t evolves as a VAR(p):

$$Y_t = \sum_{u=1}^p C_u Y_{t-u} + \varepsilon_t, \quad (1)$$

with $\varepsilon_t \sim i.i.d.N(0, \Sigma)$, $t = 1, \dots, T$, and we omit deterministic terms just for notational convenience. The number of the VAR(p) parameters grows proportionally to N^2 when p increases, becoming quickly larger than the sample size T . However, economic theory and empirical observation suggest that many economic variables tend to move together, being driven by a limited number of key structural shocks, related, for example, to productivity, financial conditions or economic policy. Formally, this suggests to impose a set of reduced rank restrictions on the C_u matrices in (1), decomposing each of them into $C_u = A_u B_0$, where each A_u is $N \times R$, B_0 is $R \times N$, and $u = 1, \dots, p$. The resulting specification, labeled Multivariate Autoregressive Index (MAI) model by Reinsel (1983) can be written as:

$$Y_t = \sum_{u=1}^p A_u B_0 Y_{t-u} + \varepsilon_t, \quad (2)$$

or

$$Y_t = \sum_{u=1}^p A_u F_{t-u} + \varepsilon_t, \quad (3)$$

where

$$F_t = B_0 Y_t. \quad (4)$$

The R variables in F_t can be considered as observable factors (indices), driving the dynamics of all the variables. Reinsel (1983) suggested to set $B_0 = (I_R, \tilde{B}_0)$ to ensure parameter identification. As R is generally much smaller than N , the MAI(p) model is much more parsimonious than the VAR(p), with a total of NRp instead of N^2p parameters in the conditional mean. This makes it computationally feasible to extend it to allow for time variation in the parameters even when N is large.

Carriero, Kapetanios and Marcellino (2016) show how to estimate the parameters of the MAI model using an MCMC algorithm, and how to select the number of factors. MAI models are a special case of general reduced-rank VARs with the advantage that they imply a VAR instead of a VARMA model for the observed factors, which is convenient for structural analysis.

Assume now that the parameters A_1, \dots, A_p change smoothly with the regime. Hence, a smooth transition MAI model is:

$$Y_t = \sum_{u=1}^p A_u F_{t-u} + \sum_{u=1}^p \Pi_t(\gamma, c, x_{t-1}) D_u F_{t-u} + \varepsilon_t, \quad (5)$$

where $\Pi_t(\gamma, c, x_{t-1})$ is a logistic function, x_t is the transition variable, c is the threshold, and γ is the smoothing parameter.¹ The model implies that if the transition variable x_{t-1} is large in comparison with the threshold c , the value of the scalar $\Pi_t(\gamma, c, x_{t-1})$ is not far from 1, and the coefficients for lag u are $(A_u + D_u)$. If instead x_{t-1} is much lower than the threshold, $\Pi_t(\gamma, c, x_{t-1})$ gets close to 0, and the coefficients are A_u . This means that D_u measures the difference in conditional mean dynamics between regimes. When the smoothing parameter γ is large, the transition function resembles a step function at the threshold c , and the parameter change is abrupt.

We assume that the regimes that characterize changes in the dynamics of the endogenous variables in Y_t are driven by one of the observable factors F_t , which are also the key drivers of

¹For surveys on smooth transition VARs, see Van Dijk, Terasvirta and Franses (2002) and Hubrich and Terasvirta (2013).

fluctuations in the variables in Y_t . Hence, we have:

$$\Pi_t(\gamma, c, x_{t-1}) = \frac{1}{1 + \exp(-(\gamma/\sigma_x)(x_{t-1} - c))}, \quad (6)$$

where $x_t = f_t^{(r)}$, that is, the transition variable is one of the R observable factors in F_t (with standard deviation σ_x):

$$f_t^{(r)} = b_0^{(r)} Y_t,$$

and $b_0^{(r)}$ the r^{th} ($1 \times N$) row of the matrix B_0 , $r = 1, \dots, R$. We use lagged factors to trigger regime changes to avoid endogeneity problems and to allow for some time delay in the adjustment of the (macroeconomic) model dynamics. We use single factors for computational simplicity and also to determine empirically which is the key driver of regime changes.²

In our empirical application, where Y_t are monthly variables generally expressed as month on month growth rates, it is convenient to set the transition variable as a smoother year-on-year growth rate:

$$x_t = g_t^{(r)} = \frac{1}{12} \sum_{j=0}^{11} b_0^{(r)} Y_{t-j}, \quad (7)$$

to capture regimes with longer duration and avoid picking up outliers. A similar smoothing is used, for example, in Auerback and Gorodnichenko (2012).

We model conditional heteroskedasticity of the $N \times 1$ vector of reduced-form disturbances ε_t as:

$$\begin{aligned} \text{var}(\varepsilon_t) &= \Sigma_t \\ \Sigma_t &= (1 - \Pi_t(\gamma, c, x_{t-1}))\Sigma_1 + \Pi_t(\gamma, c, x_{t-1})\Sigma_2, \end{aligned} \quad (8)$$

where $\Pi_t(\gamma, c, x_{t-1})$ is the logistic function as in (6). The specification implies that if the value of $\Pi_t(\gamma, c, x_{t-1})$ is near zero, then the variance-covariance matrix is near Σ_1 , but if the value of $\Pi_t(\gamma, c, x_{t-1})$ is approximately 1, then the variance-covariance matrix is at Σ_2 . As before, the transition variable x_t is the year-on-year growth equivalent of one of the factors, $g_t^{(r)}$. Note that we have just one transition function, $\Pi_t(\gamma, c, x_{t-1})$, which implies that regime changes occur at the same time in the conditional mean and variance, as for example in Auerback and

²A linear combination of a set of factors is a possible alternative, along the lines of Galvao and Marcellino (2014) who use a combination of variables in a small ST-VAR context.

Gorodnichenko (2012).

In general, when estimating large VAR models with changes in the variance-covariance matrix, many authors (Carriero, Clark and Marcellino, 2016) allow the variances to change over time (diagonal of Σ_t), while covariances (elements outside the diagonal) are fixed. Our regime-dependent smooth transition specification is a parsimonious method to also allow for covariance changes over regimes. This may have important consequences for computation of responses to structural (common) shocks.

2.2 Estimation

To estimate the ST-MAI model, we extend the Gibbs sampling algorithm for MAI models proposed in Carriero, Kapetanios and Marcellino (2016). Following Carriero, Kapetanios and Marcellino (2016), we set:

$$Z_{t-1} = (F'_{t-1}, \dots, F'_{t-p}, \Pi_t(\cdot)F'_{t-1}, \dots, \Pi_t(\cdot)F'_{t-p})',$$

where $\Pi_t(\cdot) = \Pi_t(\gamma, c, x_{t-1})$, and

$$A = (A_1 \dots A_p, D_1 \dots D_p)',$$

such that we can write the ST-MAI model as:

$$Y_t = Z_{t-1}A + \varepsilon_t$$

$$\text{var}(\varepsilon_t) = (1 - \Pi_t(\gamma, c, x_{t-1}))\Sigma_1 + \Pi_t(\gamma, c, x_{t-1})\Sigma_2.$$

The proposed algorithm includes three Metropolis steps in a Gibbs sampling approach. The algorithm has four blocks to obtain S conditional draws for all parameters.

The first block draws the parameters of the transition function similarly to Galvao and Owyang (2017). Conditional on previous draws of $\Sigma_1^{(s-1)}$, $\Sigma_2^{(s-1)}$, $A^{(s-1)}$ and $B_0^{(s-1)}$, we obtain a joint draw $\gamma^{(s)}, c^{(s)}$ using a Metropolis step, for $s = 1, \dots, S$. This assumes a gamma prior distribution for γ , and a normal distribution for c . The proposal distribution for γ is Gamma with shape parameter equal to $(\gamma^{(s-1)})^2/\Delta_\gamma$ and scale equal to $\Delta_\gamma/(\gamma^{(s-1)})$. The proposal distribution for c is a normal distribution with mean $c^{(s-1)}$ and variance Δ_c^2 . Candidate threshold

values are truncated such that at least 15% of the observations are in each regime based on the observed values of the transition variable $f_t^{(r)}$ or its yearly growth rate $g_t^{(r)}$. Both tuning parameters Δ_γ and Δ_c are set to achieve rejection rates of around 70%. In the empirical application, the prior for γ is set as a Gamma distribution with mean 15 and variance 1. The prior for c is a normal distribution with mean 0 and standard deviation 0.4.

The second block draws the parameters of the variance-covariance matrix. Conditional on $\gamma^{(s)}, c^{(s)}, A^{(s-1)}$ and $B_0^{(s-1)}$, we obtain draws for each $\Sigma_1^{(s)}$ and $\Sigma_2^{(s)}$ using an inverse-Wishart proposal distribution as in Galvao and Owyang (2017). The priors for the variance-covariance matrix of the first regime is set as $\Sigma_0^{-1} \sim W(C_0^{-1}, pv_0)$ where $C_0 = T*\underline{\Sigma}$ and $\underline{\Sigma}$ is a diagonal matrix with the variance of AR(1) processes estimated for each variable in the vector Y_t in the diagonal, and $pv_0 = N + 2$. The proposal distribution is $\Sigma_1^{-1} \sim W(C_1^{-1}, pv_1)$ with $pv_1 = pv_0 + \Delta_1 \sum_{t=1}^T I(f_{t-1}^{(i)} \leq c)$ [$I(\cdot)$ is an indicator function] and $C_1 = \Delta_{\Sigma_1} \left[\sum_{t=1}^T e_{1t} e_{1t}' \right]$ where $e_{1t} = [1 - \Pi_t(\gamma^{(s-1)}, c^{(s-1)}, x_{t-1}^{(i,s-1)})] \varepsilon_t^{(s-1)}$ and $\varepsilon_t^{(s-1)} = (Y_t - Z_{t-1}^{(s-1)} A^{(s-1)})$. In the case of the variance-covariance of the second regime, we use the same prior as for the first regime, and the proposal distribution is $\Sigma_2^{-1} \sim W(C_2^{-1}, pv_2)$ where $pv_2 = pv_0 + \Delta_2 \sum_{t=1}^T I(f_{t-1}^{(i)} > c)$ and $C_2 = \Delta_{\Sigma_2} \left[\sum_{t=1}^T e_{2t} e_{2t}' \right]$ where $e_{2t} = [\Pi_t(\gamma^{(s-1)}, c^{(s-1)}, x_{t-1}^{(i,s-1)})] \varepsilon_t^{(s-1)}$. This Metropolis-step has a rule for rejecting a proposed draw that evaluates the new draw against the old draw using the likelihood, the prior, and the proposal weights. This is applied separately for each $\Sigma_1^{(s)}$ and $\Sigma_2^{(s)}$, that is, $\Sigma_1^{(s)}$ is obtained conditional on $\Sigma_2^{(s-1)}$, and then $\Sigma_2^{(s)}$ is obtained conditional on $\Sigma_1^{(s)}$. The two tuning parameters Δ_{Σ_1} and Δ_{Σ_2} are set to achieve rejection rates of 70%. This differs from the random walk metropolis approach of Auerback and Gorodnichenko (2012), who draw each element of the variance-covariance matrix independently.

The third block draws the parameters of the matrix A . Conditional on $\Sigma_1^{(s)}, \Sigma_2^{(s)}, \gamma^{(s)}, c^{(s)}$ and $B_0^{(s-1)}$, we obtain a draw for $A^{(s)}$ using the triangularization proposed by Carriero, Clark and Marcellino (2016). The prior mean is zero for all values in A because the VAR is estimated in growth rates. The prior variance is set as:

$$\begin{aligned} \text{var}(A_{(l)}^{ij}) &= \frac{\lambda_1^2}{l\lambda_3} \sigma_i^2 \text{ if the variable } i \text{ loads in the factor } j \text{ (for } l = 1, \dots, p) \\ \text{var}(A_{(l)}^{ij}) &= \frac{\lambda_1^2 \lambda_2}{l\lambda_3} \sigma_i^2 \text{ if the variable } i \text{ does not load in the factor } j. \end{aligned}$$

The prior variance of the difference between regimes $D_1 \dots D_p$ is set as the prior for $A_1 \dots A_p$.

The fourth block draws the parameters employed in the computation of the factors. Condi-

tional on $\Sigma^{(s)}$, $A^{(s)}$ and $\gamma^{(s-1)}$, $c^{(s-1)}$, the draw $B_0^{(s)}$ is obtained using a random-walk-metropolis step as described in Carriero, Kapetanios and Marcellino (2016). This step has a tuning parameter Δ_b calibrated to achieve rejection rates of around 70%. This random-walk step employs proposal distribution variances based on factors estimated by principal component over a pre-sample period.

We also estimate a MAI specification as benchmark for the ST-MAI model and to assess the effects of nonlinearities. Carriero, Kapetanios and Marcellino (2016) use conjugate priors (normal-Wishart) for obtaining draws of A and Σ to estimate the MAI model. We use independent priors in the MAI and ST-MAI specifications, as similar priors can be also employed in the specifications with conditional heteroskedasticity. This assumption has the advantage that we are able to compare specifications using information criteria. Specifically, because $var(\varepsilon_t) = \Sigma$ in the MAI model, we substitute the second block above as follows. The draw $\Sigma^{(s)}$ is from an inverse-Wishart $\Sigma^{-1} \sim W(C_1^{-1}, pv_1)$ where $C_1^{-1} = \left(\sum_{t=1}^T \varepsilon_t^{(s)} \varepsilon_t^{(s)'} \right)^{-1} + (0.01\mathbf{I}_{(N)})^{-1}$ (\mathbf{I} is an identity matrix), $pv_1 = T + pv_0$ and $pv_0 = 120$. Finally, the first block is not required.

2.3 Responses to common structural shocks

If we multiply equation (5) by B_0 , we get:

$$F_t = B_0 \sum_{u=1}^p A_u F_{t-u} + B_0 \sum_{u=1}^p G_t(\gamma, c, x_{t-1}) D_u F_{t-u} + u_t, \quad (9)$$

with

$$u_t = B_0 \varepsilon_t, \quad var(u_t) = \Omega_t = B_0 \Sigma_t B_0'.$$

The model in (9) is a smooth transition VAR for the observable factors F_t . Hence, while the matrix B_0 that determines the composition of the factors is stable, the factor dynamics exhibit regime changes over time.

Our main interest is to measure asymmetries in the transmission of the structural shocks to the factors, v_t , underlying the reduced form shocks, u_t . Because of the nonlinear dynamics in the model, we need to compute generalized responses (Koop, Pesaran and Potter, 1996). Specifically, we compute two responses conditional to each regime at the time of the shock, but we allow for regime changes after the shock.

The impact effect of structural shocks to the observable factors, the common shocks, are

computed as in Carriero, Kapetanios and Marcellino (2016). We compute responses under the assumption that we are either in regime 1 or regime 2 at the time of the shock. It is important to emphasize, however, that later regime changes are allowed as a consequence of the shocks. Indeed, in section 3.3, we measure the probability of regime changes to evaluate asymmetries arising from the size and the sign of shocks.

Assume first that we want to compute responses when the economy is initially in regime 1. We first apply a Cholesky decomposition of the variance-covariance matrix of the factor shocks u_t to identify the R structural shocks:

$$\Omega_1 = B_0 \Sigma_1 B_0' = P_1 P_1',$$

where P_1 is a lower triangular matrix. Then, the impact of the r^{th} common structural shock at regime 1 is computed as

$$v_1^{(r)} = \Sigma_1 B_0' P_{1(r)}^{-1'}$$

where $P_{1(r)}^{-1'}$ means we use a specific column referring to common shock r of the matrix $P^{-1'}$ ($r = 1, \dots, R$).³

Similarly, if we are initially in regime 2, the impact of the shock is:

$$v_2^{(r)} = \Sigma_2 B_0' P_{2(r)}^{-1'} \text{ where } \Omega_2 = P_2 P_2'.$$

The responses of the vector Y_t to shock $v^{(r)}$ at horizon h conditional on the history at t are:

$$GR_{h,r,t} = E[Y_{t+h}|I_t, v^{(r)}; A, B_0, \Sigma_{t+h}|I_t, \gamma, c] - E[Y_{t+h}|I_t; A, B_0, \Sigma_{t+h}|I_t, \gamma, c] \quad (10)$$

where $I_t = (Y_t', \dots, Y_{t-p+1}')$ and $A = (A_1 \dots A_p, D_1 \dots D_p)'$. In other words, the $GR_{h,r}$ is the difference between $\hat{Y}_{t+h|v^{(r)}}$, which estimates the value of Y at $t+h$ after the shock $v^{(r)}$ hits the system, and \hat{Y}_{t+h} , which estimates values for the same variable assuming that only usual shocks hit the system. In both cases, the average paths $\hat{Y}_{t+1|v^{(r)}}, \dots, \hat{Y}_{t+h|v^{(r)}}$ and $\hat{Y}_{t+1}, \dots, \hat{Y}_{t+h}$ are computed using K simulated paths for Y values obtained with usual shocks from $\varepsilon_{t+h}^{(k)} \sim N(0, \Sigma_{t+h}^{(k)})$ where $k = 1, \dots, K$.⁴

The variance-covariance matrix of the usual shocks depends on the smooth transition func-

³Other identification methods are of course possible but, as we will see, the Cholesky approach can be well justified in our empirical application and it produces interesting and sensible results.

⁴In the empirical application, we set K to 100.

tion, which is a function of x_{t+h-1} , which in turn is a linear combination of Y_{t+h-1} . This implies that Σ_{t+h} is affected by the shock $v^{(r)}$ and may change as $h = 1, \dots, H$. Hence, for each path k , Y values are simulated using:

$$\begin{aligned}\varepsilon_{t+h}^{(k)} &\sim N(0, \Sigma_{t+h|t}^{(k)}) \\ \Sigma_{t+h|t}^{(k)} &= (1 - \Pi_{t+h}(\gamma, c, x_{t+h-1}^{(k)}))\Sigma_1 + \Pi_{t+h}(\gamma, c, x_{t+h-1}^{(k)})\Sigma_2.\end{aligned}$$

An implication of equation (10) is that we have one response function over horizons $h = 1, \dots, H$ to the shock $v^{(r)}$ at each point in time (I_t for $t = p + 1, \dots, T$). For clarity, we present responses that are averaged over a set of histories defined by the estimated regimes. This implies that we compute responses conditional on the regime at the impact. Define $I^{(reg1)}$ as the histories I_t such that $\Pi_t(\gamma, c, x_{t-1}) < 0.5$ for $t = p + 1, \dots, T$, and $I^{(reg2)}$ as the history values such that $\Pi_t(\gamma, c, x_{t-1}) \geq 0.5$.⁵ Then the generalized responses conditional on regime 1 are:

$$\begin{aligned}GR_{h,r}^{reg1} &= 1/T_1 \sum_{t=1}^{T_1} GR_{h,r,t}^{(reg1)} \\ GR_{h,r,t}^{(reg1)} &= E[Y_{t+h}|I_t^{(reg1)}, v_1^{(r)}; A, B_0, \Sigma_{t+h}|I_t^{(reg1)}, \gamma, c] \\ &\quad - E[Y_{t+h}|I_t^{(reg1)}; A, B_0, \Sigma_{t+h}|I_t^{(reg1)}, \gamma, c]\end{aligned}\tag{11}$$

where T_1 is the number of observations in the regime 1 history, that is, the number of times that $\Pi_t(\gamma, c, x_{t-1}) < 0.5$ holds.⁶ Similarly for regime 2:

$$\begin{aligned}GR_{h,r}^{reg2} &= 1/T_2 \sum_{t=1}^{T_2} GR_{h,r,t}^{(reg2)} \\ GR_{h,r,t}^{(reg2)} &= E[Y_{t+h}|I_t^{(reg2)}, v_2^{(r)}; A, B_0, \Sigma_{t+h}|I_t^{(reg2)}, \gamma, c] \\ &\quad - E[Y_{t+h}|I_t^{(reg2)}; A, B_0, \Sigma_{t+h}|I_t^{(reg2)}, \gamma, c].\end{aligned}\tag{12}$$

⁵We could also employ different thresholds to split the sample across regimes. For example, we could define the first regime as $G_t(\gamma, c, x_{t-1}) < 0.3$, and the second regime as $G_t(\gamma, c, x_{t-1}) > 0.7$. This would remove intermediary observations to sharpen regime identification. In our empirical application, estimates of γ are large, implying almost no observations in these intermediary values, and that small changes on how we define regime-dependent histories do not affect our results.

⁶We accumulate the responses over horizons after the computation in (11) because all variables in Y_t are in growth rates.

2.3.1 Algorithm to compute responses

The computation of the responses above is for a given set of parameters values $(A^{(j)}, B_0^{(j)}, \Sigma^{(j)}, \gamma^{(j)}, c^{(j)})$.

We use J equally-spaced draws from the posterior distribution of the parameters to compute $GR_{h,r,t}^{reg1,(j)}$ and $GR_{h,r,t}^{reg2,(j)}$ with the aim of incorporating parameter uncertainty ($j = 1, \dots, J$).

Then our estimated response to the common shock r at regime 1 is the mean of $GR_{h,r,t}^{reg1,(j)}$ for $j = 1, \dots, J$, and confidence bands are computed using percentiles (16%, 68%) based on the same set of values $GR_{h,r,t}^{reg1,(j)}$. The complete algorithm for the computation of these regime-dependent responses at time of the shock is:

1. Draw a set of parameters – $A^{(j)} = (A_1^{(j)}, \dots, A_p^{(j)}, D_1^{(j)}, \dots, D_p^{(j)})$, $B_0^{(j)}$, $\Sigma_1^{(j)}$, $\Sigma_2^{(j)}$, $\gamma^{(j)}$, $c^{(j)}$ – from saved posterior distribution draws.
2. Using the transition function $\Pi_t(\gamma^{(j)}, c^{(j)}, x_{t-1}^{(j)})$, define the set of regime 1 and regime 2 histories ($I_t^{(reg1)}$ and $I_t^{(reg2)}$).
3. Using the $A^{(j)}$, $B_0^{(j)}$, $\Sigma^{(j)}$, $\gamma^{(j)}$, $c^{(j)}$ and the set of histories from regime 1, compute a set of K paths with and without the impact of $v_1^{(r)}$ for each history $t = 1, \dots, T_1$. These paths are $Y_{t+1|v_1^{(r)}}^{(k)}, \dots, Y_{t+h|v_1^{(r)}}^{(k)}$ and $Y_{t+1}^{(k)}, \dots, Y_{t+h}^{(k)}$ for $k = 1, \dots, K$, where K is the number of replications to approximate the conditional means. Based on the average over the K paths, we obtain $\widehat{Y}_{t+1|v_1^{(r)}}, \dots, \widehat{Y}_{t+h|v_1^{(r)}}$ and $\widehat{Y}_{t+1}, \dots, \widehat{Y}_{t+h}$ for each set of histories. These paths are obtained by simulating the system using draws from $\varepsilon_{t+h}^{(k)} \sim N(0, \Sigma_{t+h|t}^{(k)})$. This implies that we simulate paths also for $\Sigma_{t+1|v_1^{(r)}}^{(k)}, \dots, \Sigma_{t+h|v_1^{(r)}}^{(k)}$ and $\Sigma_{t+1}^{(k)}, \dots, \Sigma_{t+h}^{(k)}$. The regime 1 responses are computed by taking the differences between the average paths (with and without the shock) for each history, and then obtaining regime 1 response as the average response over all regime 1 histories.
4. Using the $A^{(j)}$, $B_0^{(j)}$, $\Sigma^{(j)}$, $\gamma^{(j)}$, $c^{(j)}$ and the set of histories from regime 2, compute the paths as described in step 3 but using the shock $v_2^{(r)}$ for each history $t = 1, \dots, T_2$. Compute then the regime 2 responses by taking the differences between the average paths (with and without the shock) for each history, and then computing the average response over all regime 1 histories.
5. Repeat 1-4 for $j = 1, \dots, J$.
6. Use $GR_{h,r}^{reg1,(j)}$ and $GR_{h,r}^{reg2,(j)}$ for $j = 1, \dots, J$ to compute the median response and 68% confidence intervals conditional on each regime and for $h = 1, \dots, H$.

2.3.2 Sign and Size Asymmetries

In addition to amplification effects depending on the regime at the time of shock, ST-MAI models are also able to deliver significant different responses to positive and negative shocks. First, to simplify the notation, write:

$$GR_{h,r,t}(v^{(r)}) = E[Y_{t+h}|I_t, v^{(r)}; A, B_0, \Sigma_{t+h}|I_t, \gamma, c] - E[Y_{t+h}|I_t; A, B_0, \Sigma_{t+h}|I_t, \gamma, c].$$

Hence, asymmetries from the sign of the shock are computed as:

$$ASY_{h,r,t}^{+-} = GR_{h,r,t}(v^{(r)}) - GR_{h,r,t}(-v^{(r)}).$$

The larger are the differences between responses to positive and negative shocks, the larger is $ASY_{h,r,t}$ (in absolute value). We modify the algorithm described in section 2.3.1 to compute $ASY_{h,r,t}^{+-(\text{reg1})}$ in step 3 and $ASY_{h,r,t}^{+-(\text{reg2})}$ in step 4. This implies we aim to compute:

$$\begin{aligned} ASY_{h,r}^{+-(\text{reg1})} &= 1/T_1 \sum_{t=1}^{T_1} \left[GR_{h,r,t}^{(\text{reg1})}(v_1^{(r)}) - GR_{h,r,t}^{(\text{reg1})}(-v_1^{(r)}) \right] \\ ASY_{h,r}^{+-(\text{reg2})} &= 1/T_2 \sum_{t=1}^{T_2} \left[GR_{h,r,t}^{(\text{reg2})}(v_2^{(r)}) - GR_{h,r,t}^{(\text{reg2})}(-v_2^{(r)}) \right] \end{aligned}$$

As in the case of the responses, we compute 68% confidence bands for each asymmetry measure at horizons $h = 1, \dots, H$. These bands are employed to assess whether positive and negative shocks have statistically different effects by evaluating whether either $ASY_{h,r}^{+-(\text{reg1})}$ or $ASY_{h,r}^{+-(\text{reg2})}$ are nonzero.

We also consider asymmetries from the size of the shock. The shocks implied by the impact vector $v_1^{(r)}$ and $v_2^{(r)}$ are equivalent to one-standard deviation shocks, so we call these shock as "small". We consider two-standard deviation equivalent impacts $2v_1^{(r)}$ and $2v_2^{(r)}$ as large shocks. We measure asymmetries for the size of shock conditional on each one of the regimes at the impact as:

$$\begin{aligned} ASY_{h,r}^{ls(\text{reg1})} &= 1/T_1 \sum_{t=1}^{T_1} \left[GR_{h,r,t}^{(\text{reg1})}(2v_1^{(r)}) - 2 * GR_{h,r,t}^{(\text{reg1})}(v_1^{(r)}) \right] \\ ASY_{h,r}^{ls(\text{reg2})} &= 1/T_2 \sum_{t=1}^{T_2} \left[GR_{h,r,t}^{(\text{reg2})}(2v_2^{(r)}) - 2 * GR_{h,r,t}^{(\text{reg2})}(v_2^{(r)}) \right]. \end{aligned}$$

If large shocks have different effects from small shocks in, say, regime 2, we expect that $ASY_{h,r}^{ls(reg2)}$ will be nonzero for a set of horizons and shocks. As before, we use different draws from the posterior distribution of the parameters to compute 68% confidence bands for these asymmetry measures as the main values are obtained using the median as described in section 2.3.1.

2.4 Choosing the number of factors and the transition variable

A key component for the specification of the ST-MAI model is the choice of the number of factors, and of the factor to be used as transition variable.

To decide the number of factors for (constant parameter) MAI models, Carriero, Kapetanios and Marcellino (2016) suggest to use the marginal data density (MDD). However, the MDD of ST-MAI models is not available analytically, and limited experimentation with computational approaches was not satisfactory. However, the number of factors in a MAI model can be indicative of that in the corresponding ST-MAI model. As an alternative, the choice can be driven by economic considerations, or alternative specifications can be compared according to other criteria, such as penalized in-sample fit or forecasting capacity. In our empirical application, we set the number of factors to four to aid the identification of four common structural shocks even though the MDD approach when applied to the MAI model as in Carriero, Kapetanios and Marcellino (2016) prefers a specification with three factors.

After setting the number of factors, we need a procedure to select a transition variable from the set of factors (or other relevant variables). As mentioned, we are not able to use the marginal data density. Hence, we propose to use the Bayesian information criterion (BIC).

Assuming that θ is the vector of all the model parameters, such that $\ln f(y|\theta)$ is the log-likelihood value at a given set of parameters θ , where $y = \{Y_t\}_{t=p+1}^{t=T}$, the BIC is then

$$BIC = -2E_\theta[\ln f(y|\theta)] + \ln(T-p)[2NRp + N - R], \quad (13)$$

where $E_\theta[\ln f(y|\theta)]$ is estimated by averaging the likelihood over the kept MCMC draws, and the penalty term is set for the ST-MAI specification. Because the penalty term will not vary with the choice of transition variable over alternatives $g_t^{(1)}, \dots, g_t^{(R)}$, the use of BIC to choose the transition variable is equivalent to maximize the average likelihood.

3 Credit Conditions and the Effects of Economic Shocks

We now want to exploit the econometric set-up we have built to address a set of empirical questions. First, do credit conditions trigger regime changes in the dynamic relationships among economic variables? Second, do they amplify the effects of economic shocks? Third, do they generate sign/size asymmetries in the effects of economic shocks?

We use a data set of 20 monthly (endogenous) variables for the USA, which includes the economic activity, monetary and price variables in the "medium" dataset of Bańbura et al. (2010) plus additional indicators of credit conditions, as described in Table 1. As our sample includes the zero lower bound period, we use the end-of-period effective fed fund rates for most months, except for the period where the zero lower bound is binding, where we use the Wu and Xia (2015) shadow rate as published in the Atlanta Fed website. We also use the one-year Treasury bill to help to capture the effects of unconventional monetary policy. We use six variables to measure credit conditions. The first one is the excess bond premium computed using corporate bond yields by Gilchrist and Zakrajsek (2012). This measure was employed by Lopez-Salido et al. (2017) to measure confidence in the credit market. The remaining five spread measures have been considered by Hatzius et al. (2010) and are also part of financial stress indices periodically released by regional Feds (Chicago, St. Louis and Cleveland). The set of spreads include the 3-month commercial paper spread over the 3-month Treasury bill, which was employed as transition variable by Balke (2000). It also includes the term spread measured by the difference between 10 year and 3-month Treasury rates.

The sample period is from 1974M1 up to 2016M8, but the period up to 1982M2 is employed as pre-sample to obtain mean and variances for the proposal distributions for the random walk metropolis step employed in the estimation of the factor loadings B_0 . Variables are transformed as indicated in Table 1 and the MAI is estimated to their normalized values.

We set the number of factors to four. Basically, we add a credit factor to the real, nominal and monetary factors of Carriero, Kapetanios and Marcellino (2016). The monetary policy variables are not part of the credit factor so that we are able to disentangle monetary policy shocks from credit market shocks. Brunnermeier et al. (2017) argue in favour of this differentiation to understand the impact of credit on economic activity. Figure 1 shows the estimated factors using the MAI model. We label the factors as economic activity, inflation, monetary policy and credit following the variables that load on these factors in Table 1.

To provide a better understanding of these factors, we evaluate correlations between the

estimated factors and alternative economic indexes. Table 2 shows correlations between the annualized factors and a set of economic and financial indexes. These include the Philadelphia Fed Coincident Economic Activity index and the Chicago Fed Financial Condition Index (including the version adjusted to remove endogenous macroeconomic effects). For the computations in Table 2, we use the factors computed at the posterior mean using the MAI model.⁷

The results in Table 2 clearly suggest that the activity factor behaves as a coincident indicator. Indeed the correlation with the Philadelphia Coincident index is of 86% at the monthly frequency. The credit factor is clearly measuring financial conditions. The factor has a 78% correlation with the Chicago Fed FCI. The monetary policy factor is correlated with the activity, credit and inflation factors, with all the proper signs. We should also note that the inflation factor (which loads on four price variables) has a positive correlation (about 50%) with the Chicago Fed FCI and our credit conditions factor.

3.1 Credit conditions as transition variable

The first empirical research question to be addressed is whether credit conditions are able to characterize nonlinearities within a ST-MAI model. Table 3 presents the average likelihood and the BIC for the four different ST-MAI model specifications. They vary by the choice of factor to act as transition variable.⁸

The results in Table 3 indicate that the credit factor is the transition variable that provides the best fit for the 20 variables in the model. The second best variable to characterize regime changes is the activity factor, which is able to deliver regime changes that are highly correlated with NBER business cycle phases.

Figure 2 shows the values of the transition function using the credit factor as transition variable $[\Pi_t(\gamma, c, g_{t-1}^{(4)})]$ at the posterior mean. The dotted lines are 68% confidence bands for the transition function, and the blue line is the credit factor at the posterior mean. The Figure also includes NBER recession dates. It is clear that what we have estimated as the upper regime has anticipated both the 90-91 and the 2001 recessions. The upper regime dates also coincide with the NBER 2008-2009 recession. Following the use of credit conditions as part of financial condition indices and their use for identification of financial stress periods, we call the upper

⁷The model is estimated as described in section 2.1 with 20,000 draws where the first 4,000 are discarded for the computation of the posterior mean.

⁸The statistics are computed using 16,000 kept draws for each specification based on the listed hyperparameters' values. The hyperparameters of proposal distributions are set to achieve about 30% acceptance rates, while the overall prior tightness is set to maximize the average likelihood over a small grid values.

regime as the “high credit stress” regime and the lower regime as the “low credit stress” regime.

3.2 Credit conditions as shock amplifiers

Our previous results support the use of credit conditions to characterize changes in the dynamic relationships among the 20 variables listed in Table 1. Now we assess whether credit conditions can also cause the amplification of shocks. Specifically, we evaluate the responses to structural shocks of six key indicators selected from the 20 variables in Table 1.⁹ We have two measures of economic activity: industrial production and unemployment; two measures of credit spreads: the Gilchrist and Zakrajsek (2012) excess bond premium (EBP) and the commercial paper spread; the PCE deflator as an example of price variable; and the fed funds rate (that is equal to the shadow rate during the ZLB period) as a monetary policy measure.

As the ST-MAI model has four factors, we can identify four common shocks. We use the Cholesky-based method described in section 2.3. Following Carriero, Kapetanios and Marcellino (2016), we label the first two shocks as demand and supply shocks. Indeed, in response to the first shock, industrial production, prices and the fed fund rates move together, as in the case of a demand shock. In contrast, in response to the second shock, prices and industrial production move in opposite directions. The third shock is a monetary policy shock, and indeed industrial production and prices decline in response to this shock. The fourth shock is a credit conditions shock. The identification ordering follows Gilchrist et al. (2009), who order last the credit factor in their factor augmented VAR. This implies that the credit factor can react contemporaneously to demand, supply and monetary shocks, but it has no contemporaneous effects on them. We checked whether the effects of credit shocks are robust to changing the ordering between monetary and credit factors. We find that our median estimated values of the effects of credit shocks at impact change very little when we change the ordering.

Figures 3 to 6 show (cumulative) responses of industrial production, unemployment, the PCE deflator, the EBP, the Fed rate and the Commercial paper (CP) spread to each one of the four shocks using the ST-MAI model with credit factor as transition variable. Responses are computed for horizons from 1 up to 48 (four years) by using 200 parameters draws from the stored posterior distribution of the parameters as described in section 2.3. Dashed lines are 68% confidence bands. Responses in red assume that the shock hits in the high credit stress regime (regime 2), while responses in blue assume the shock hits in the low credit stress regime

⁹Responses for all other variables are available upon request.

(regime 1). Impact responses ($h = 1$) may change over regimes because the variance-covariance matrix of the ST-MAI model is regime dependent.

Figure 3 shows responses for a negative demand shock (an exogenous decline of the activity factor). One can observe strong amplification effects in the high stress regime in the responses of economic activity variables and prices to demand shocks. Similar sized demand shocks have their effects amplified twofold after two years if they hit in the regime of bad credit conditions. The effect of the demand shock on unemployment is an increase of about 1 percentage point after two years in times of low credit stress, but in times of high stress, this effect is 2 percentage points. An amplification of similar magnitude is also detected in the excess bond premium responses.

Similar amplification effects are also found in the responses of economic activity variables to supply shocks (Figure 4), except for the PCE deflator. Amplification effects are smaller for monetary and credit shocks (Figures 5 and 6), though still present. The response of the PCE deflator to credit is clearly amplified in the high stress regime (Figure 6). Similar results are found by Galvao and Owyang (2017): financial stress shocks have strong negative effects on prices during the high stress regime.

Interestingly, results in the response to monetary policy shocks (Figure 5) suggest that the excess bond premium increases following monetary policy tightening in the high stress regime. However, a shock of similar size has a negative effective effect on excess bond premium in the low stress regime.

These empirical results confirm the usefulness of ST-MAI models in uncovering amplification effects in the responses to structural shocks. This is achieved by allowing the parameters of the conditional mean and conditional variance to change over regimes driven by an observed set of credit spread variables. The results, obtained with a large model and with a set of credit spread measures, confirm the evidence of nonlinearity in Balke (2000), based on a small threshold VAR model with the commercial paper spread as transition variable.

3.3 Credit conditions and asymmetric shock effects

Our last empirical research question is to check whether either positive and negative shocks or large and small shocks have different effects. Before showing the results for the asymmetry measures described in section 2.3 ($ASY_{h,r}^{+-}(reg1)$, $ASY_{h,r}^{+-}(reg2)$, $ASY_{h,r}^{ls}(reg1)$, $ASY_{h,r}^{ls}(reg2)$), we use differences in the probability of regime changes after the shock as a first glance on the issue

of different responses depending on the size and the sign of the shock. Table 4 presents the probability of staying in the same regime as the one at impact over a 12-month period after the shock. Recall that in the ST-MAI model the variables that trigger regime changes are endogenous so that, even if a shock hits the economy during the low stress regime, there is a probability that after one year the economy switches to the high stress regime. Table 4 explores the effect of different sizes and signs of the shock on this probability, based always on the same set of histories at the time of shock. We consider our four identified structural shocks for cases they are either positive or negative and are small (equivalent to one-standard deviation) and large. The results in Table 4 clearly show that the size and the sign of the shocks have virtually no effect on the likelihood to switch to the high stress regime when at the time of the shock the model is in the low credit stress regime. Because the low stress regime covers 80% of the period, this suggests that normally positive and negative shocks and small and large shocks have very similar effects. However, during the high stress regime, good shocks (positive demand shock, negative supply shock, loosening of monetary policy stance and decrease in credit spreads) increase the likelihood of moving out of the high credit stress regime. Because the transition variable measures credit conditions, a large shock improving credit conditions ($-2v_2$) delivers a probability of switching to the low stress regime of 42%, while this probability is of only 18% if we change the sign of the shock. These results suggest that the duration of the high credit stress regime depends on the shocks hitting the economy once we are in the high stress regime. It is reassuring that loosening the monetary policy improves the probability of regime switching to 36% after one year.

Next, we compute the asymmetry measures described in section 2.3 for all the 20 variables in the VAR and for each of the four common shocks. We use 68% confidence bands to assess whether there are statistically significant asymmetries. For responses computed to shocks in the low credit stress regime at impact, we find no evidence of significant asymmetry. Figure 7 shows estimates of $ASY_{h,r}^{ls(reg2)}$ for the unemployment, the fed fund rate and the commercial paper spread as responses to each of our four common shocks and for $h = 1, \dots, 24$. We choose these variables because they are the ones that normally exhibit asymmetries during the high credit stress regime. Figure 7 indicates that positive and negative demand shocks have symmetric effects, but supply, monetary policy and credit shocks have asymmetric effects, that is, large shocks have disproportionate stronger effects than small shocks. A large shock to credit spreads increases significantly more unemployment even though the fed funds rate downward movement

is disproportionately larger. This might be explained by the stronger effects on commercial paper spread, which measures short run corporate market riskiness. These results suggest that the size of the shock matters if the economy is in a credit stress regime. They support the theoretical implications discussed in Krishnamurthy and Muir (2017) but also add evidence that it is not only financial shocks that generate asymmetric effects, but also inflationary and monetary policy shocks.

Figure 8 shows estimates of $ASY_{h,r}^{+-(reg2)}$ for unemployment and commercial paper spread. There are sign asymmetries for large (two-standard deviation) shocks. Figure 8A shows estimates as responses to supply shocks, and the following figures present values for monetary policy and credit shocks. Figure 8C shows industrial production instead of unemployment so we can compare our results with Barnichon et al. (2017). All asymmetry values are negative. As positive shocks lead to positive responses in the variables presented (unemployment and commercial paper spread), then significant negative values of $ASY_{h,r}^{+-(reg2)}$ imply that negative shocks – a decrease in prices, loosening of monetary policy stance, narrowing of credit spreads – have a larger effect on these variables than positive ones. The largest negative effects are detected for the responses to supply shocks. In Figure 8D we present, as an example, unemployment and commercial paper spread responses to positive (blue) and negative (red) shocks in the high stress regime. It is clear that these responses are not symmetric and that a shock that deflates prices reduces unemployment by 3 percentage points after two years, while a positive shock of the same size increases unemployment by a bit more than 1 percentage point after two years.

The detected asymmetries in the response of unemployment to shocks imply that unemployment can strongly decrease after two years if good shocks hit the economy at the time of credit stress. This nonlinear propagation effect of credit conditions on unemployment is, as far as we are aware, novel in the empirical literature. This shows again the usefulness of a large time-varying VAR model when assessing the links between credit conditions and the macroeconomy.

Barnichon et al. (2017) empirical results suggest that shocks that improve credit supply (negative shocks in our case) have muted effects on industrial production while shocks that contract credit supply have strong negative effects on industrial production. Their effects were computed using a nonlinear projection approach, assuming that responses differ depending on the sign of the past shocks. Our results suggest that an unexpected improvement in credit

conditions may have a stronger effect in increasing growth than a deterioration would have if at the time of the shock we are in the high credit stress regime. These dissimilar results can be reconciled if we consider the responses in Figure 5 of Barnichon et al. (2017) as regime-dependent responses for a high stress regime (credit supply contraction) and for a low stress regime (credit supply expansion). This is a reasonable assumption if we consider that positive credit supply shocks are more likely during the low stress regime and negative credit supply shocks are more likely in the high stress regime. Their responses are then similar to the ST-MAI responses to credit tightening shocks in Figure 6. The flexibility of the impulse response analysis based on the ST-MAI model allows us to better understand what it is really driving changes in the transmission of credit shocks, and how US data support the implications of theoretical models as summarized by Krishnamurthy and Muir (2017).

3.4 Small Smooth Transition VAR model

We claim in the introduction of this paper that by including more variables in a VAR, we enlarge the information set employed to compute impulse responses and that this might be beneficial for structural analysis, as it alleviates omitted variable bias and permits a more granular analysis of the effects of the shocks. In this subsection we estimate a smooth transition VAR with five variables to check if we are able to replicate our main empirical results with this smaller model. The five variables described in Table 1 that we included in this small VAR are: industrial production, unemployment, CPI, fed fund rate (+ shadow rate) and the EBP credit spread measure. The model is as in Barnichon et al. (2017), except that we include unemployment. We estimate the ST-VAR using MCMC blocks 1 to 3 of the estimation procedure described in section 2.2. As before, we use the data transformations in Table 1 and $p = 13$. We use the EBP as transition variable.

Figure 9 shows the estimated regime changes. The correlation with the regime changes estimated in Figure 3 is of only 58%. There is a longer upper regime between 2000 and 2003 and the upper regime lags the NBER recession in 2008. We compute the BIC for this model using the average likelihood and compare it with the BIC for the ST-MAI model for the fit of the five variables included in the small ST-VAR model. The BIC supports the ST-MAI model even if it estimates fewer parameters than the ST-VAR (when $R = 4$).

We use a Cholesky decomposition to identify the shocks, using the variable ordering above. Figure 10 presents (cumulative) responses with 68% bands for the upper and the lower regime

at the time of shock. We compute responses for IP (activity) shocks, CPI (inflation) shocks, Fed rate (monetary policy, MP) shocks and EBP (credit) shocks. This exercise is designed to be comparable with Figures 3 to 6. In general, the responses to inflation and credit shocks are similar to the responses computed with the large ST-MAI model, while responses of activity and MP shocks are very different (the response to MP shocks does not change with credit conditions!). We conclude that, even though in this application one does not necessarily need a large model to measure the effects of credit shocks, the large MAI model helps to capture the effects of other important shocks by enlarging the information set employed in the computation of the responses, and it also permits to assess the effects of the shocks on a larger number of variables.

4 Conclusions

This paper sheds additional light on the relationship between credit conditions and the macroeconomy. We show that credit stress, as measured by widening spreads, can alter the dynamic relationships among economic variables. Moreover, during credit stress periods, the effects of economic shocks can be amplified, and there can be sign and size asymmetries, so that positive and negative shocks of the same size can have different effects (in absolute value) and small and large shocks of the same sign can also have asymmetric effects.

These empirical features emerge from a novel econometric model, a large smooth transition multivariate autoregressive index (ST-MAI) model. In the ST-MAI model all variables are driven by a small number of observable factors, and their lags. In our case, we have economic activity, prices, monetary and credit factors. The credit factor is also the preferred transition variable, the trigger of parameter changes, with a reasonable timing for the endogenously identified credit stress periods.

We develop a (Bayesian) estimation procedure for the ST-MAI model, and show how it can be used to compute (generalized) impulse response functions and measures of asymmetry.

We believe that, besides our specific application, the ST-MAI model can be a useful tool for empirical macroeconomics, as it permits to model large set of variables, taking into account parameter changes across regimes. It is similar to a factor augmented vector autoregressive (FAVAR) model, but the observable factors simplify estimation, shock identification, and interpretation of the results.

Our empirical results suggest that the duration of financial fragility episodes depends crucially on the type, size and sign of the shocks hitting the economy. Episodes can be shorter if large good shocks hit the economy. Fortunately, policy makers are able to control one of these good shocks – the monetary policy shock – and we are able to show that by loosening the monetary policy stance, policy makers increase the probability of moving out from a financial stress episode after one year.

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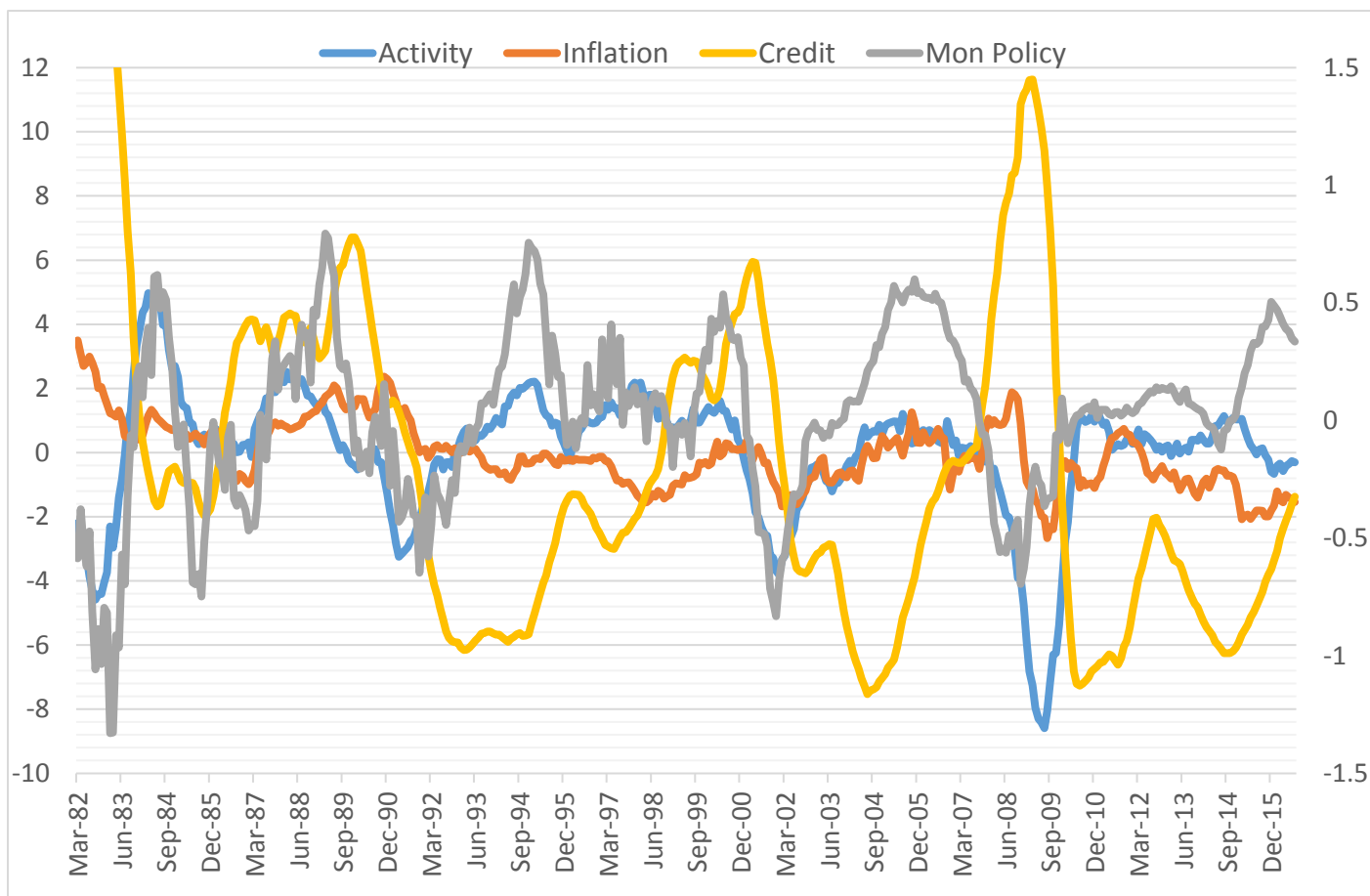
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Table 1: List of endogenous variables in the (ST) MAI specifications.

	Factor	Trans.
Employees nonfarm	activity	Log-diff
Avg hourly earnings	activity	Log-diff
Personal income	activity	Log-diff
Consumption	activity	Log-diff
Industrial Production	activity	Log-diff
Capacity utilization	activity	Log-diff
Unemp. Rate	activity	Log-diff
Housing Starts	activity	Log-diff
CPI	inflation	Log-diff
PPI	inflation	Log-diff
PCE deflator	inflation	Log-diff
PPI ex food and energy	inflation	Log-diff
FedFunds + shadow rate	Mon. Pol.	diff
1year_rate	Mon. Pol.	diff
EBP	Credit	levels
BAA spread	Credit	levels
Mortgage Spread	Credit	levels
TED Spread	Credit	levels
CommPaper Spread	Credit	levels
Term Spread (10y-3mo)	Credit	levels

Note: sample period 1974M1-2016M8. Data between 1974M1 and 1982M2 is employed as pre-sample.

Figure 1: Factors estimated by MAI in annual differences.



Note: Monetary policy factor in the right axis.

Table 2: Correlations among and with MAI estimated factors

	F_infl	F_mp	F_cred	PhilFed Activity	Chicago Fed Fin Cond.	Adj. Chicago Fed Fin Cond.
F_activity	0.06	0.61	-0.47	0.86	-0.39	-0.02
F_inflation	1	-0.13	0.48	-0.11	0.54	0.12
F_mp	-0.13	1	-0.49	0.63	-0.34	-0.07
F_credit	0.48	-0.49	1	-0.51	0.78	0.53

Table 3: Measures of fit for different ST-MAI specifications

	Average Likelihood	BIC
F_activity as trans. var. ($\lambda_1=1; \Delta_\Sigma=25/110; \Delta_{\gamma,c}=0.01$)	-7820.760	28271.735
F_inflation as trans. var. ($\lambda_1=1; \Delta_\Sigma=120/20; \Delta_{\gamma,c}=0.01$)	-8004.157	28638.529
F_mp as trans. var. ($\lambda_1=1; \Delta_\Sigma=20/120; \Delta_{\gamma,c}=0.01$)	-7859.639	28349.943
F_credit as trans. var. ($\lambda_1=1; \Delta_\Sigma=120/20; \Delta_{\gamma,c}=0.01$)	-7749.376	28128.967

Note: All specifications with 4 factors set as in Table 1. Hyperparameters are chosen to maximise the average likelihood and/or set acceptance rates to about 30%.

Figure 2: Regime changes in ST-MAI model with F_credit as Regime-Switching Variable.

Figure 2A: Transition function over time

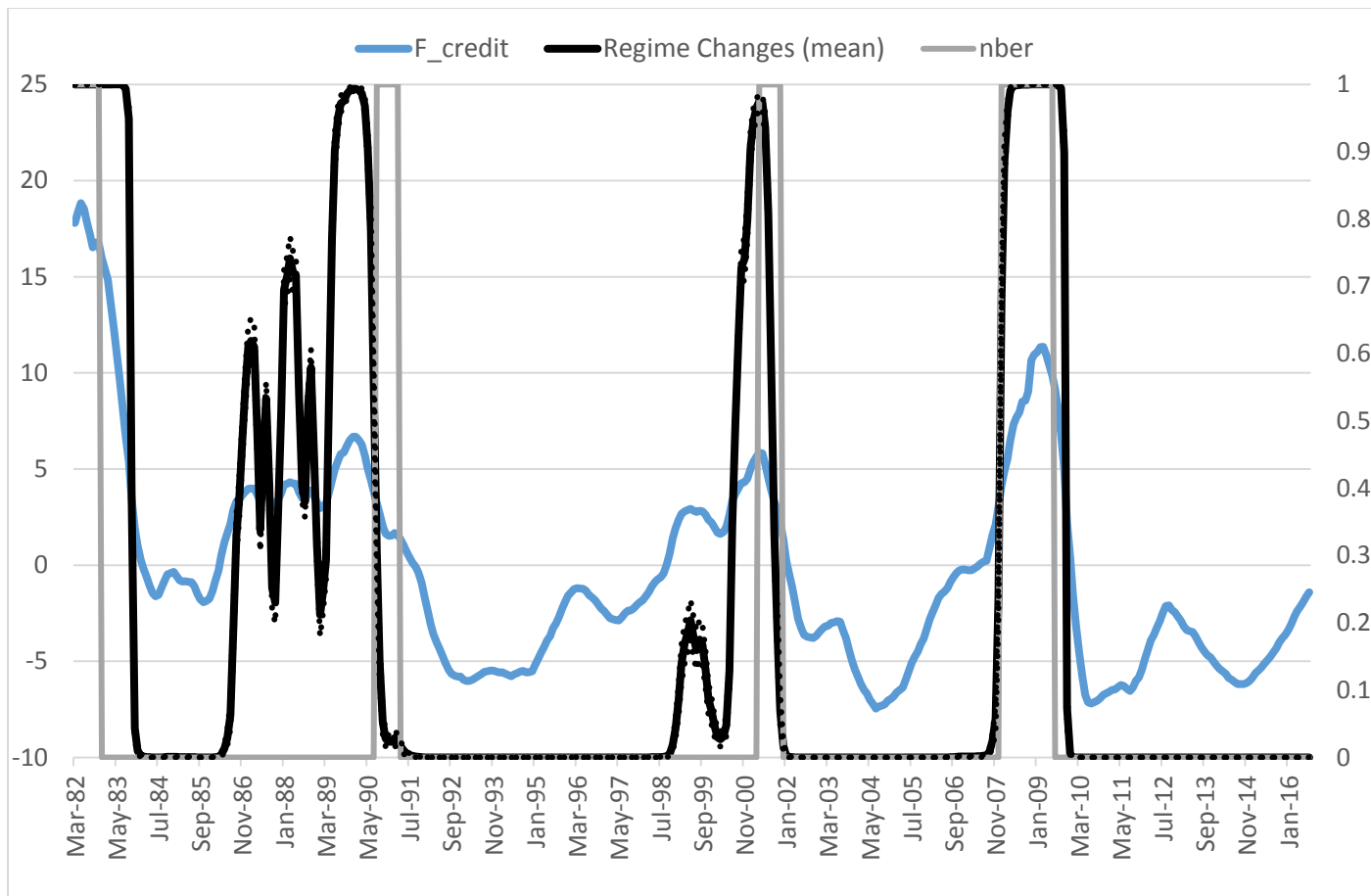


Figure 2B: Scatter plot of transition function for values of F_credit at posterior mean parameters

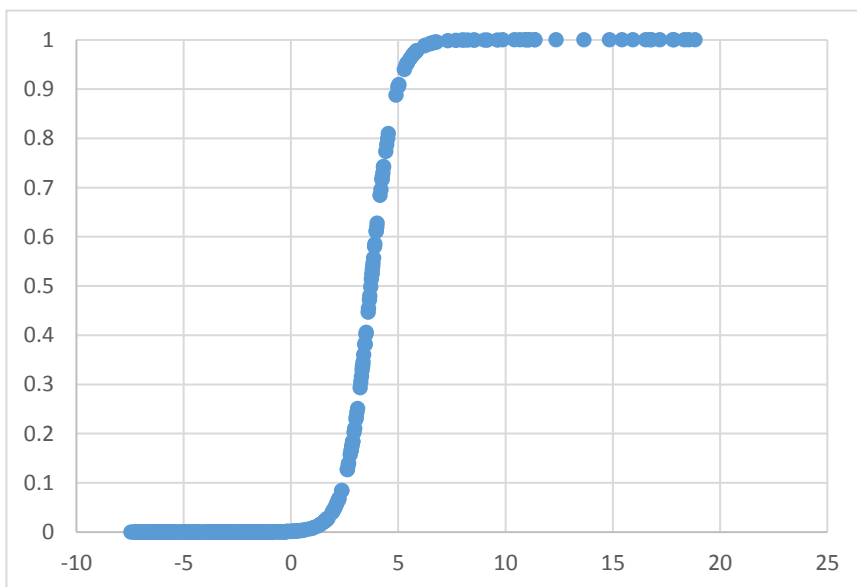
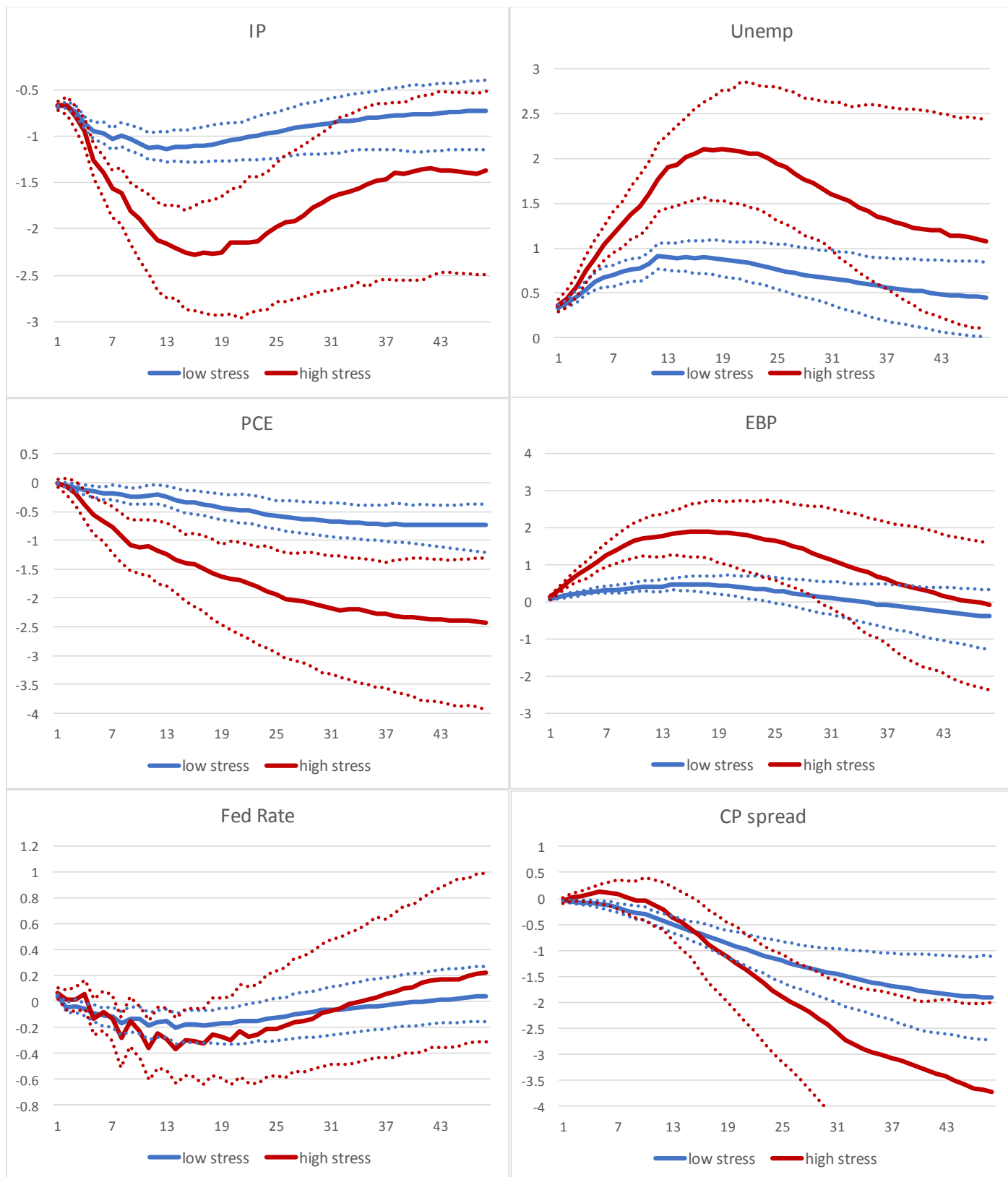
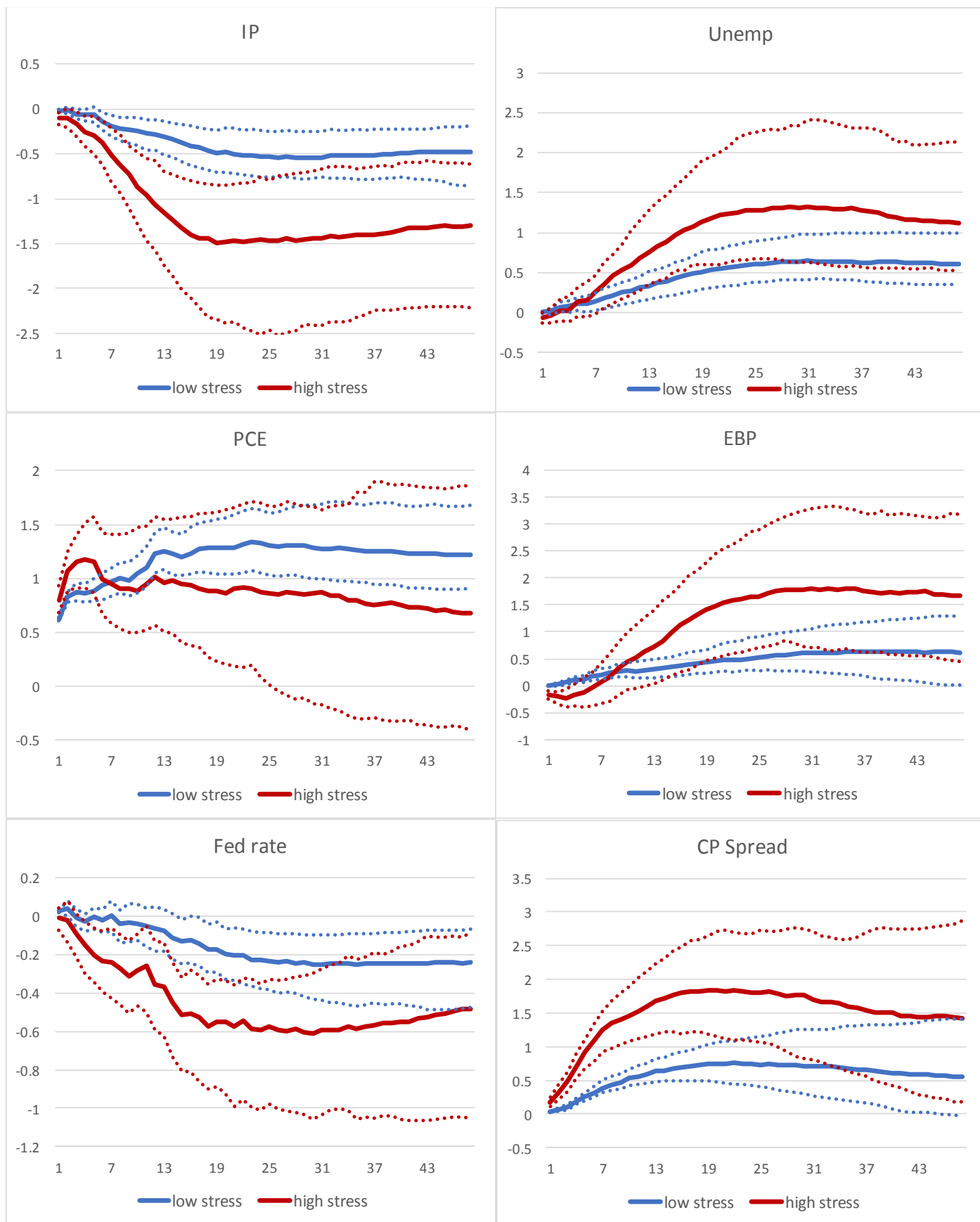


Figure 3: ST-MAI model responses to demand shock



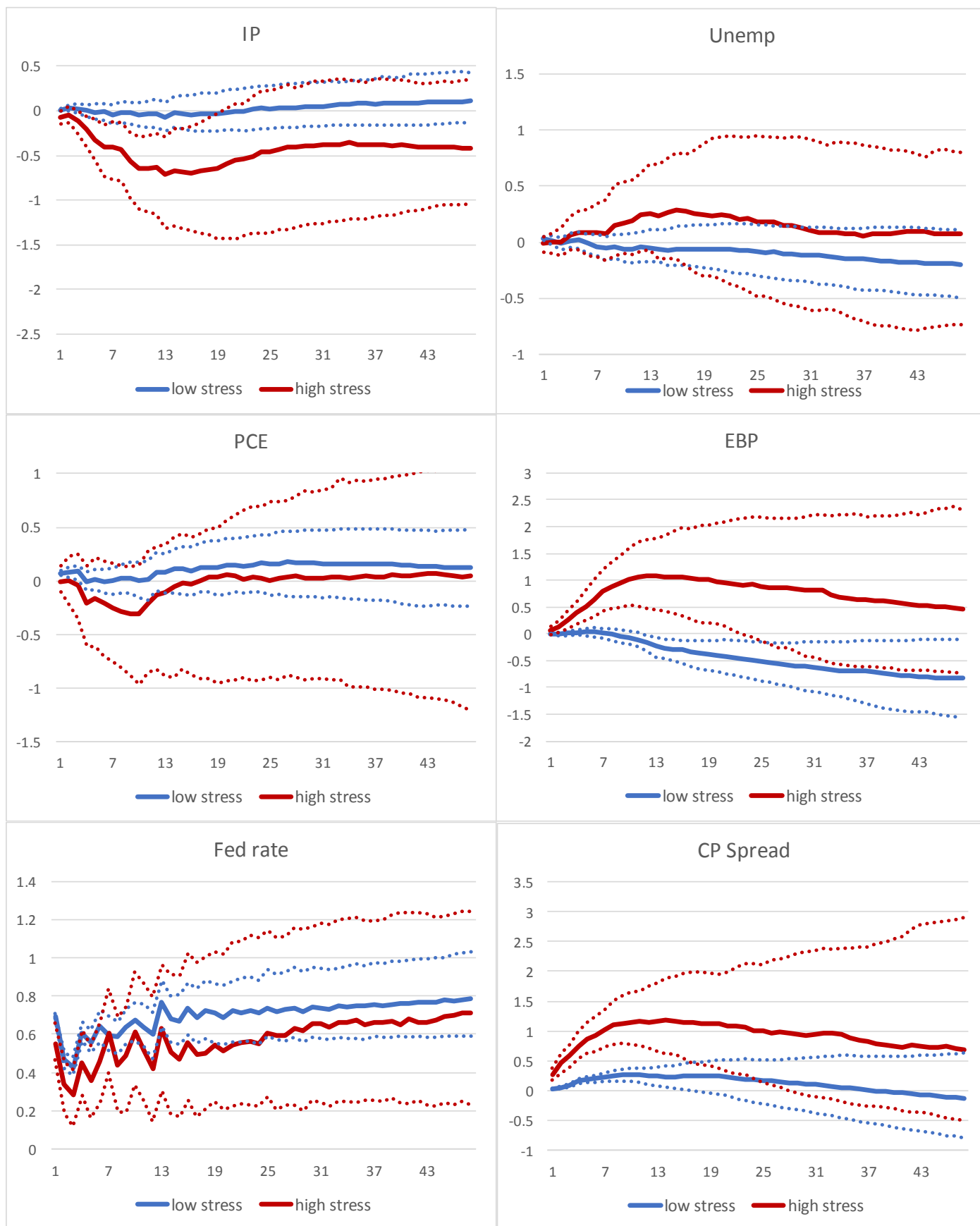
Note: Dotted lines are 68% confidence bands.

Figure 4: ST-MAI model responses to supply shock



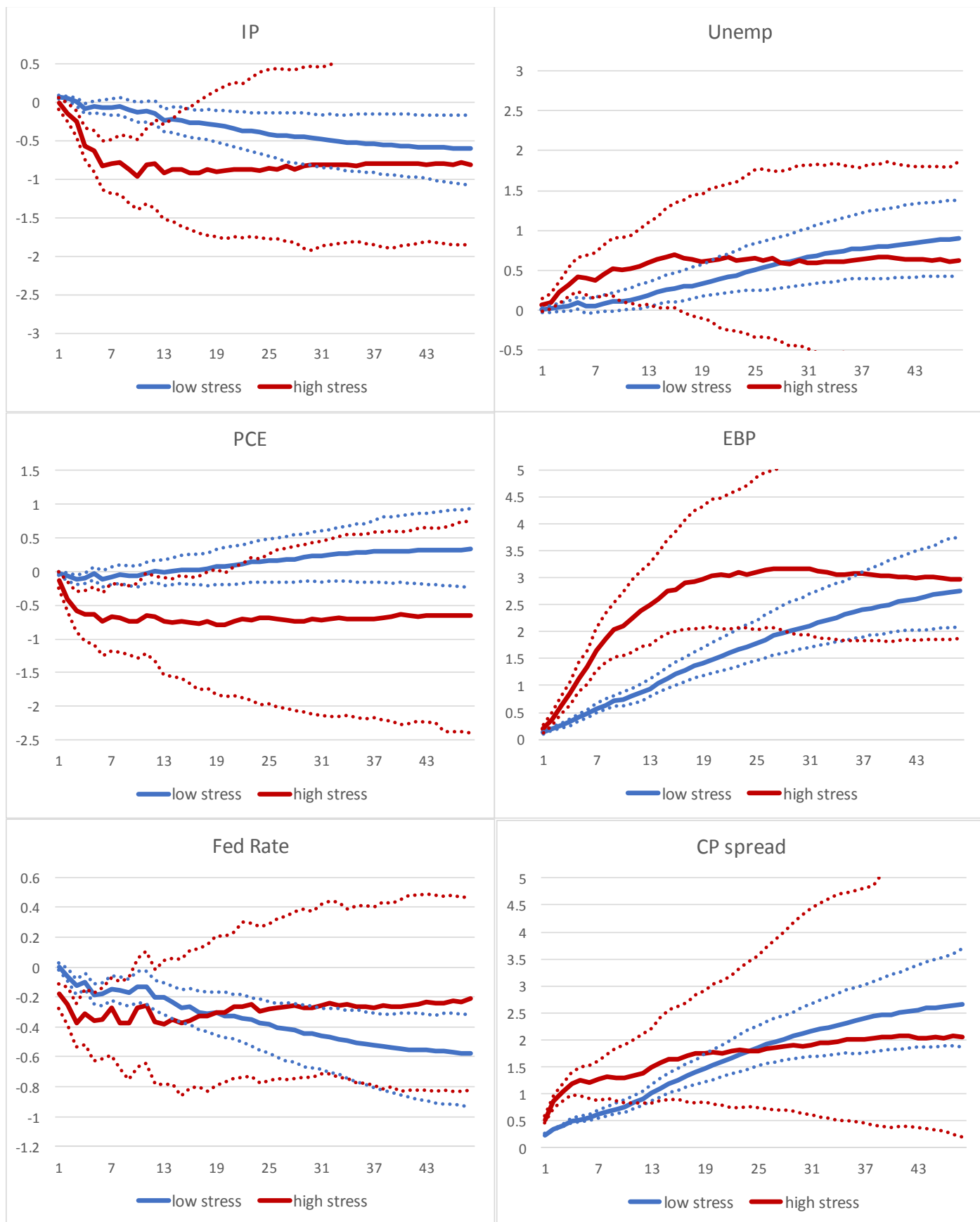
Note: Dotted lines are 68% confidence bands.

Figure 5: ST-MAI model responses to monetary policy shock



Note: Dotted lines are 68% confidence bands.

Figure 6: ST-MAI model responses to credit shocks



Note: Dotted lines are 68% confidence bands.

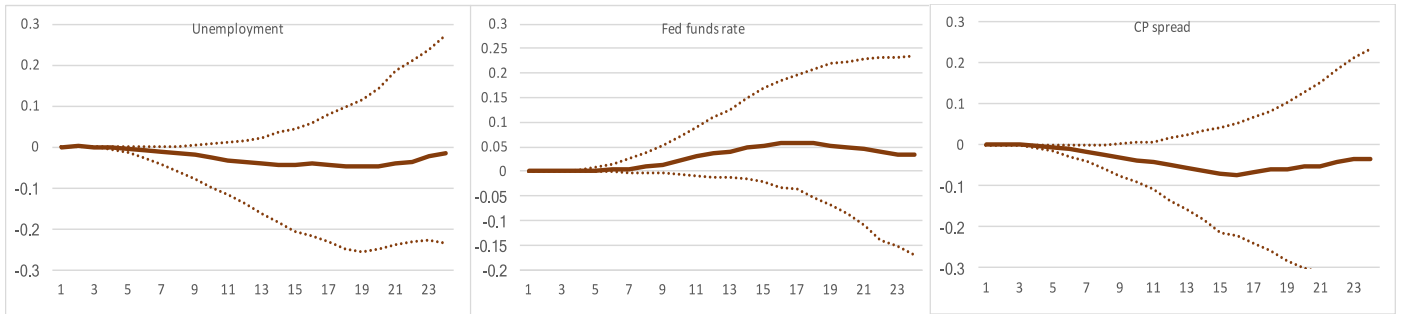
Table 4: Probability of staying at the regime at the impact of the shock over a 12-month period after the shock

Regime at time of the shock:	Low Stress Regime		High Stress Regime	
	Positive shocks			
Type of shock:	Small (v_1)	Large ($2v_1$)	Small (v_2)	Large ($2v_2$)
Demand (activity) shock	0.96	0.96	0.70	0.69
Supply (price) shock	0.95	0.95	0.74	0.77
Monetary policy shock	0.95	0.95	0.74	0.77
Credit (spread) shock	0.94	0.93	0.77	0.82
	Negative shocks			
	Small ($-v_1$)	Large ($-2v_1$)	Small ($-v_2$)	Large ($-2v_2$)
Demand (activity) shock	0.96	0.96	0.72	0.72
Supply (price) shock	0.96	0.97	0.67	0.64
Monetary policy shock	0.96	0.96	0.67	0.64
Credit (spread) shock	0.97	0.98	0.64	0.58

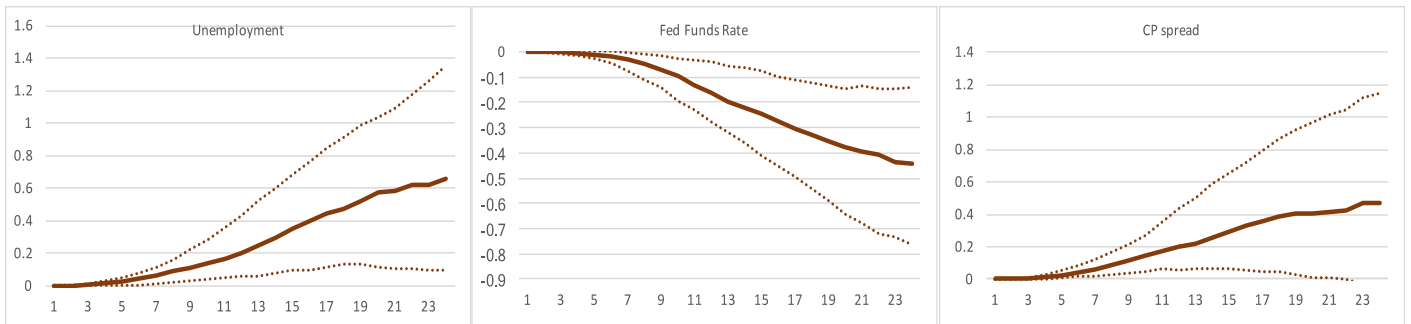
Note: These are the proportion from the total number of horizons (12) that we do not observe regime changes as response for each specified shock. These are computed with parameters at the posterior mean and using 200 usual shock draws ($K=200$ in section 2.3) to compute the conditional expectation after the shock.

Figure 7: Differences between responses to large ($2*v$) and small (v) shocks in the high stress regime.

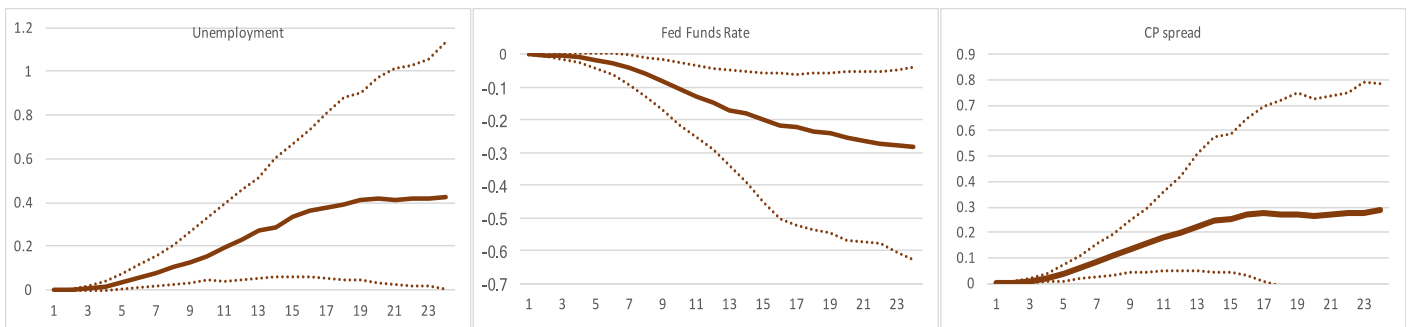
7A: Demand (activity) shocks.



7B: Supply (price) shocks



7C: Monetary Policy shocks



7D: Credit Spread shocks

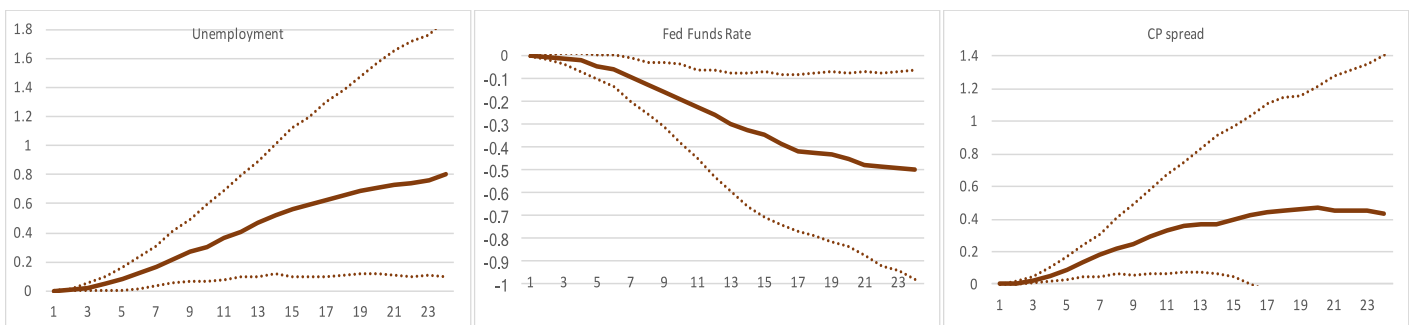


Figure 8: Differences between responses to positive ($2*v$) and negative ($-2*v$) shocks in the high stress regime

Figure 8A: Supply (prices) shocks

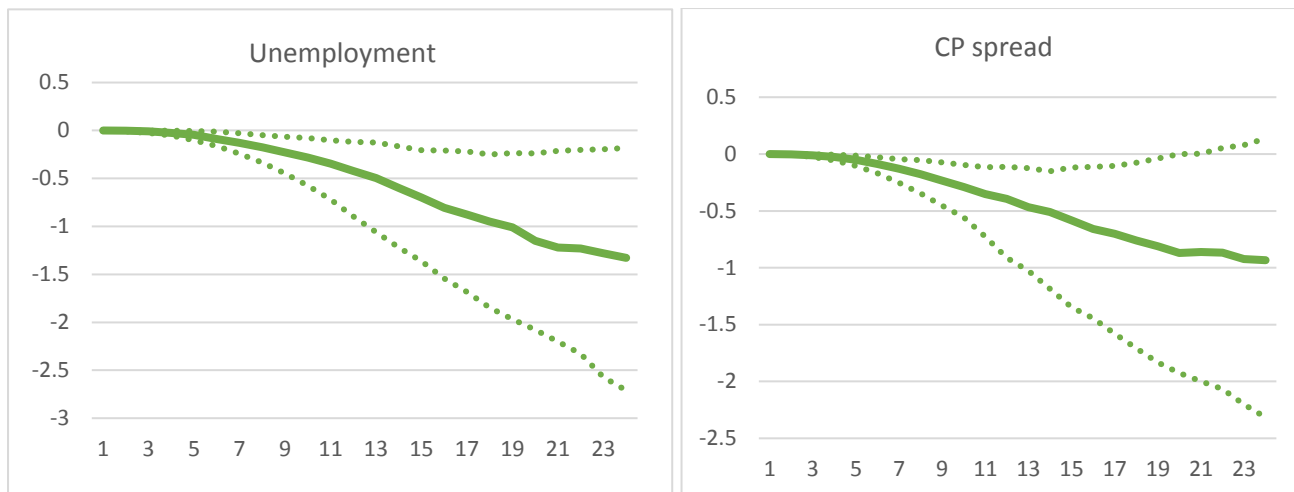


Figure 8B: Monetary Policy shocks

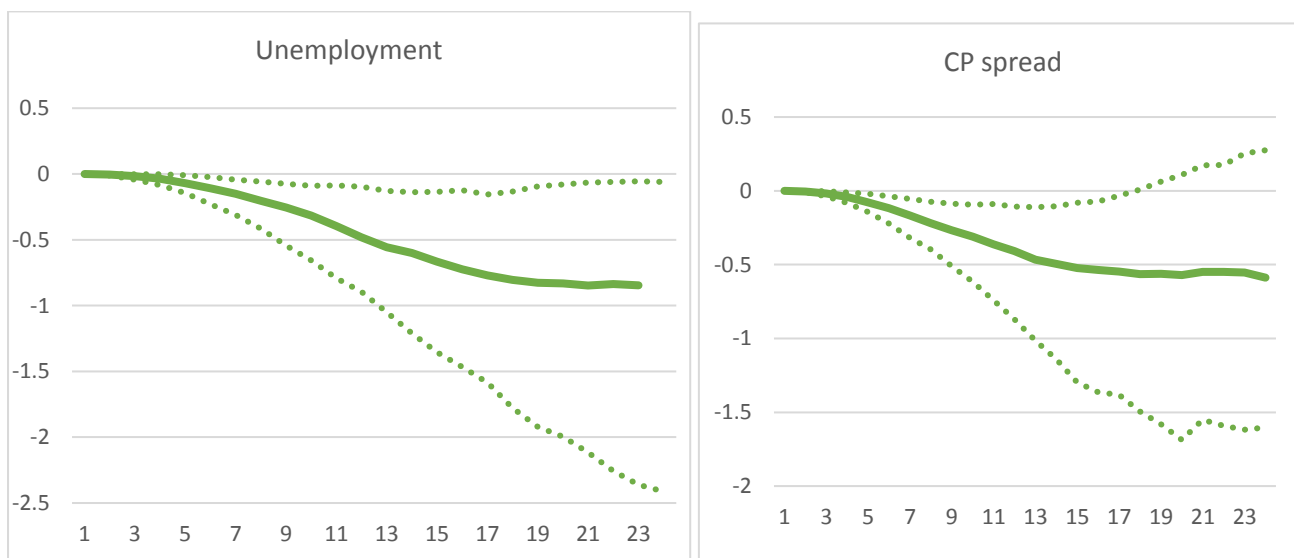


Figure 8C: Credit Spread shocks

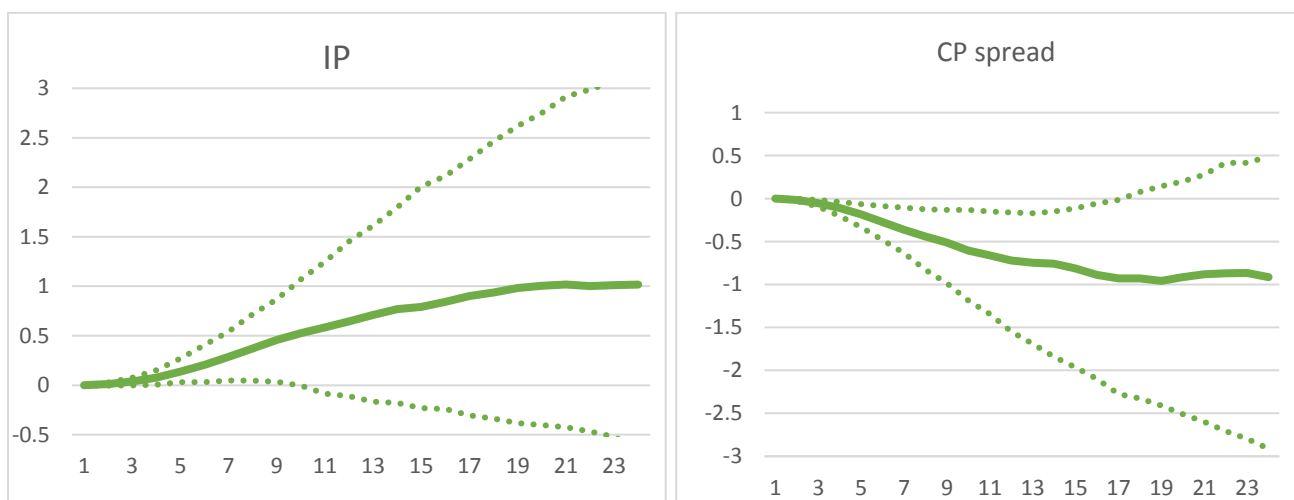


Figure 8D: Responses to a small supply shock in the high stress regime

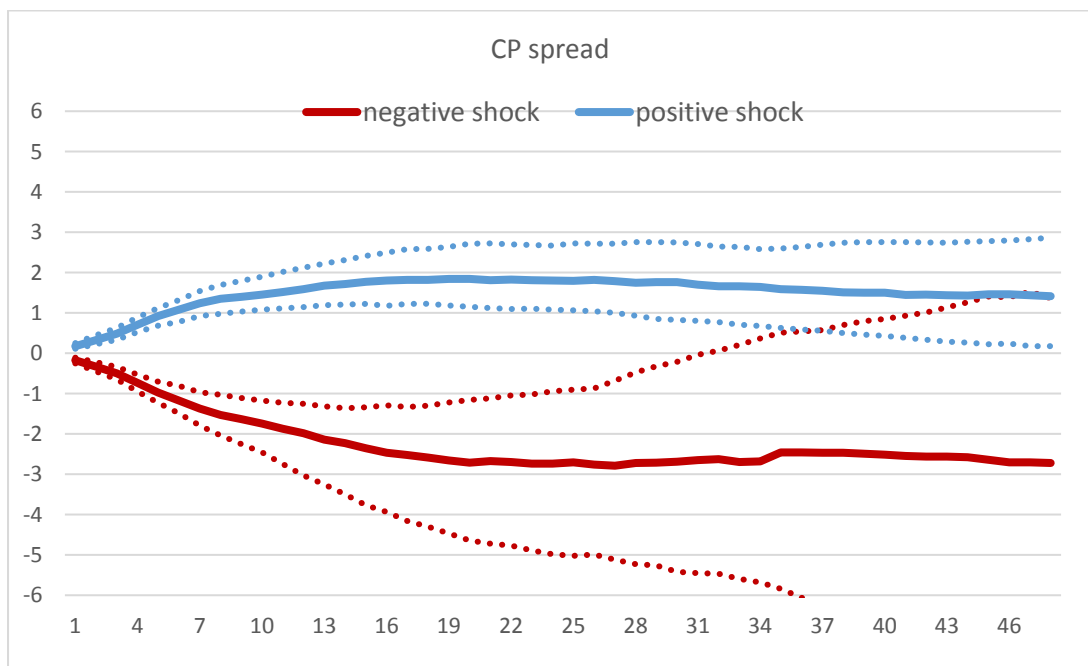
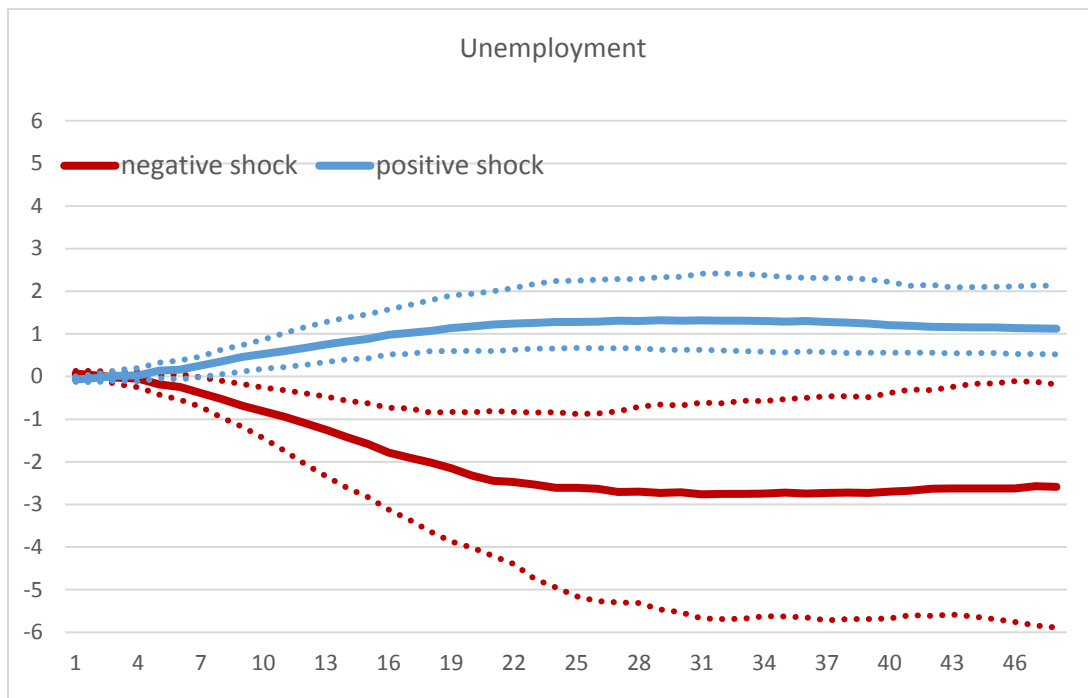


Figure 9: Regime changes in ST-VAR model of 5 variables with EBP as Regime-Switching Variable.

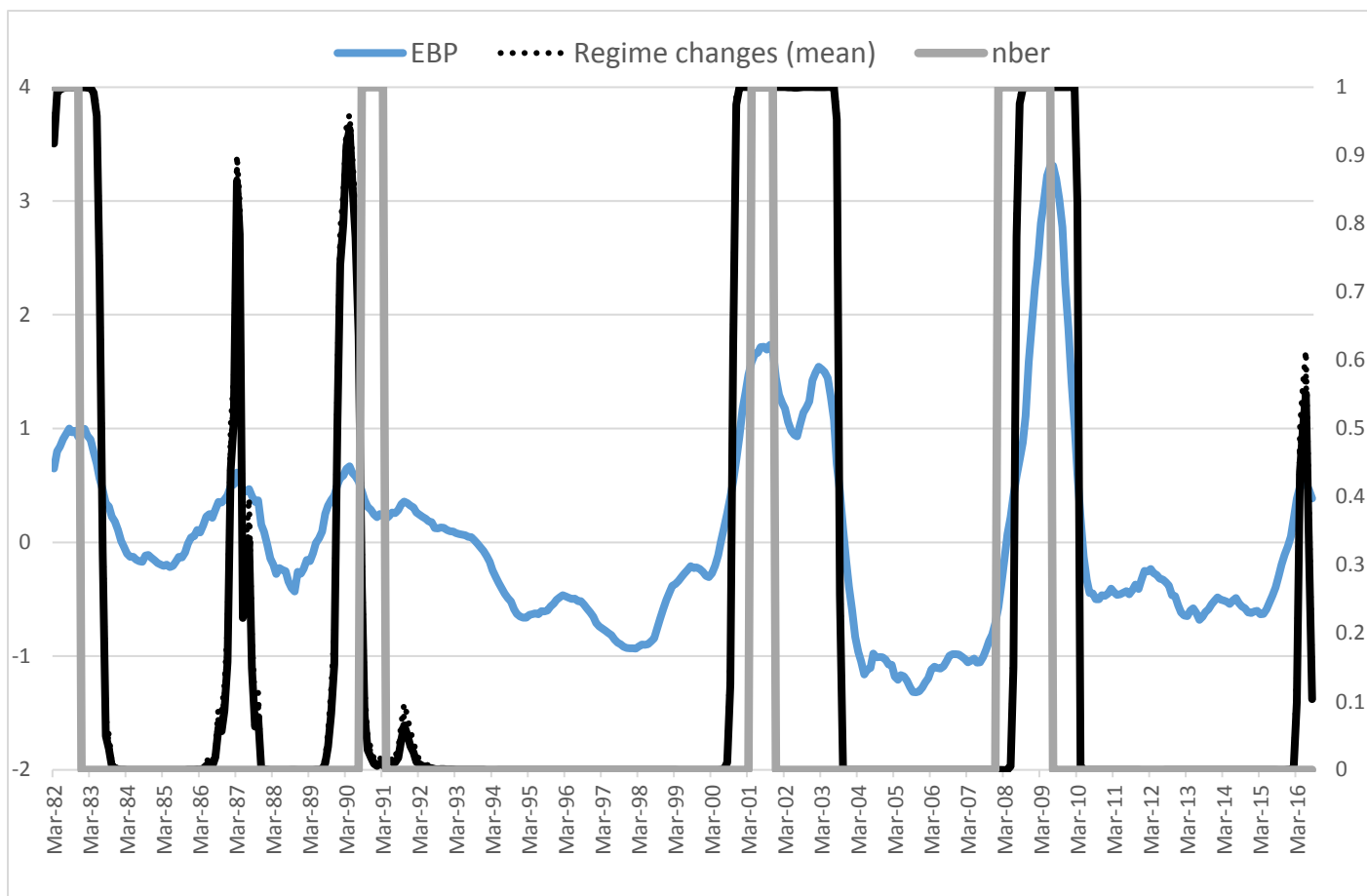


Figure 10: Responses of the ST-VAR model with 5 variables

Figure 10A: Responses to IP growth shocks

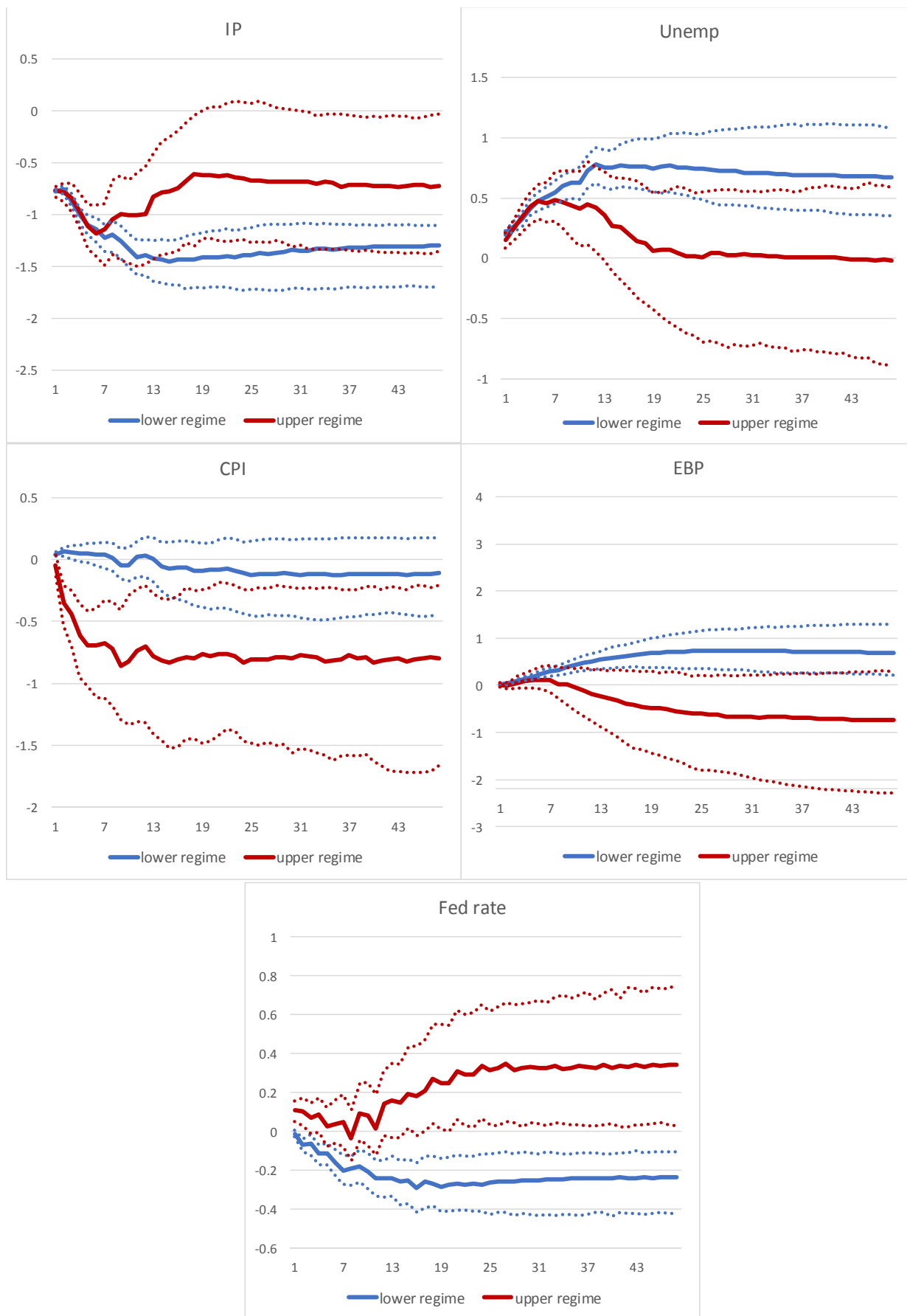


Figure 10B: Responses to CPI inflation shocks

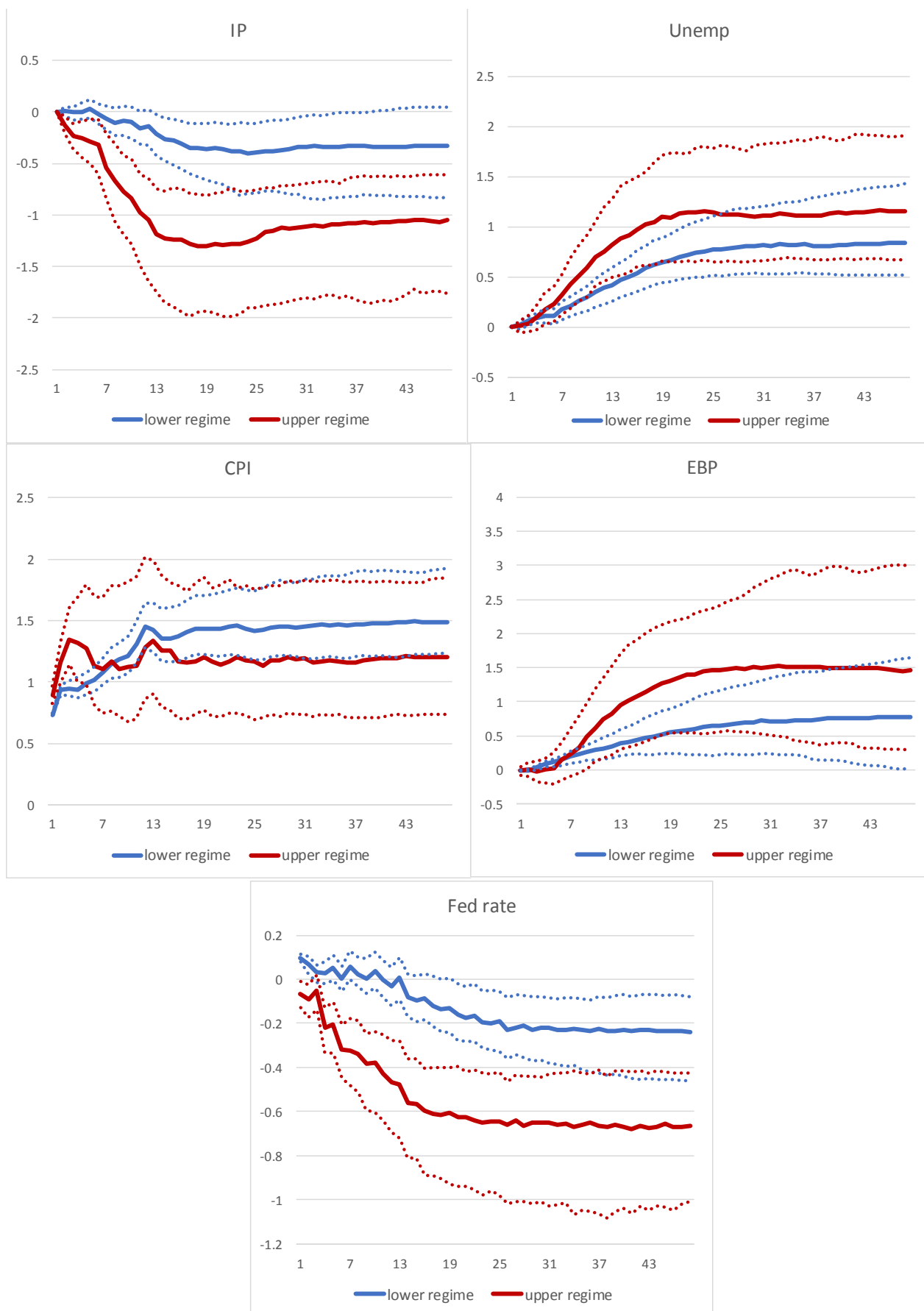


Figure 10C: Responses to Fed fund rate (MP) shocks

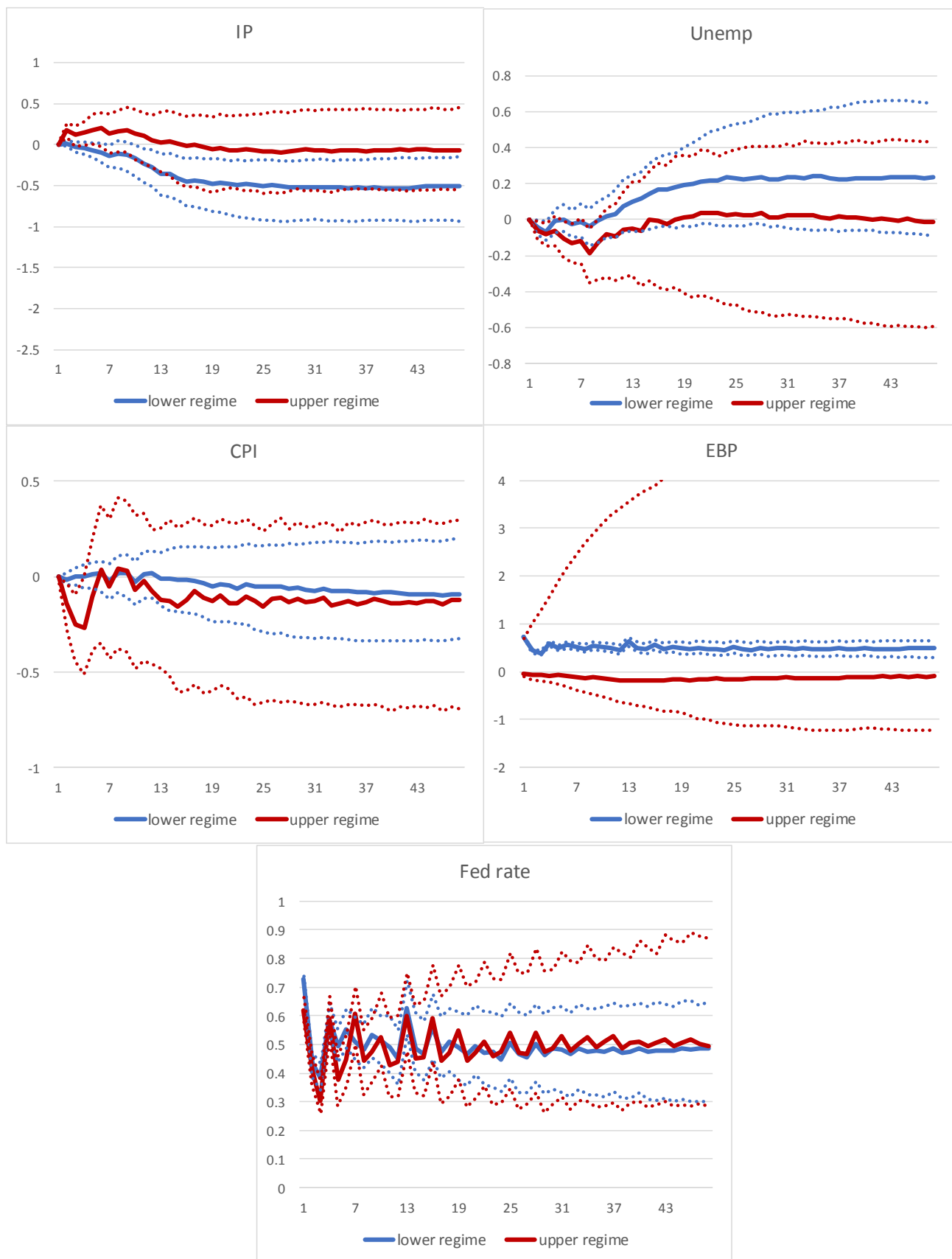


Figure 10D: Responses to EBP (credit spread) shocks

